

End-to-End Modeling of
Marine Ecosystems: can the
people and data keep up with
the computers?

Kenneth Rose
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What is End-to-End?

Travers et al. (2007):

(1) aims to represent the entire food web and the associated abiotic environment

(2) requires the integration of physical and biological processes at different scales

(3) implements two-way interaction between ecosystem components

(4) accounts for the dynamic forcing effect of climate and human impacts at multiple trophic levels

Rose (2013):

(1+) multiple species or functional groups be represented at each of the key trophic levels and that top predators in the system are included

(4+) representation of the physics be such that it can be modified by climate inputs and that the human aspect (e.g. fishery) be represented in a dynamic (state-dependent) manner

Development of a Climate-to-Fish-to-Fishery Model:

Implementation in the Eastern Pacific
Sardine and Anchovy System

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CAPaBLE



ARSC DoD Supercomputing Resource Center



North Pacific Marine Science Organization



NOAA HPC High Performance Computing and Communications



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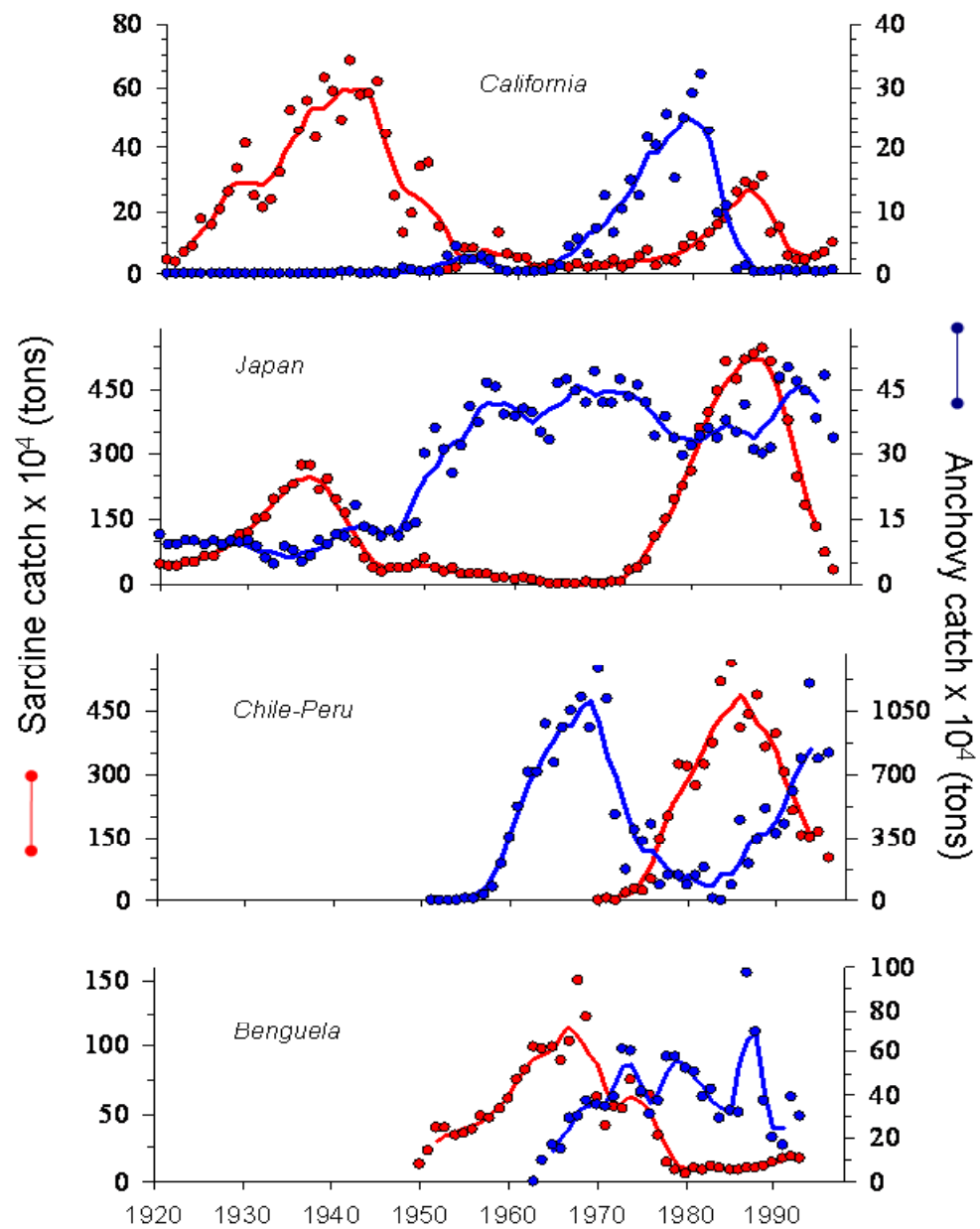
Francisco Werner
NOAA Fisheries - SWFSC

Introduction

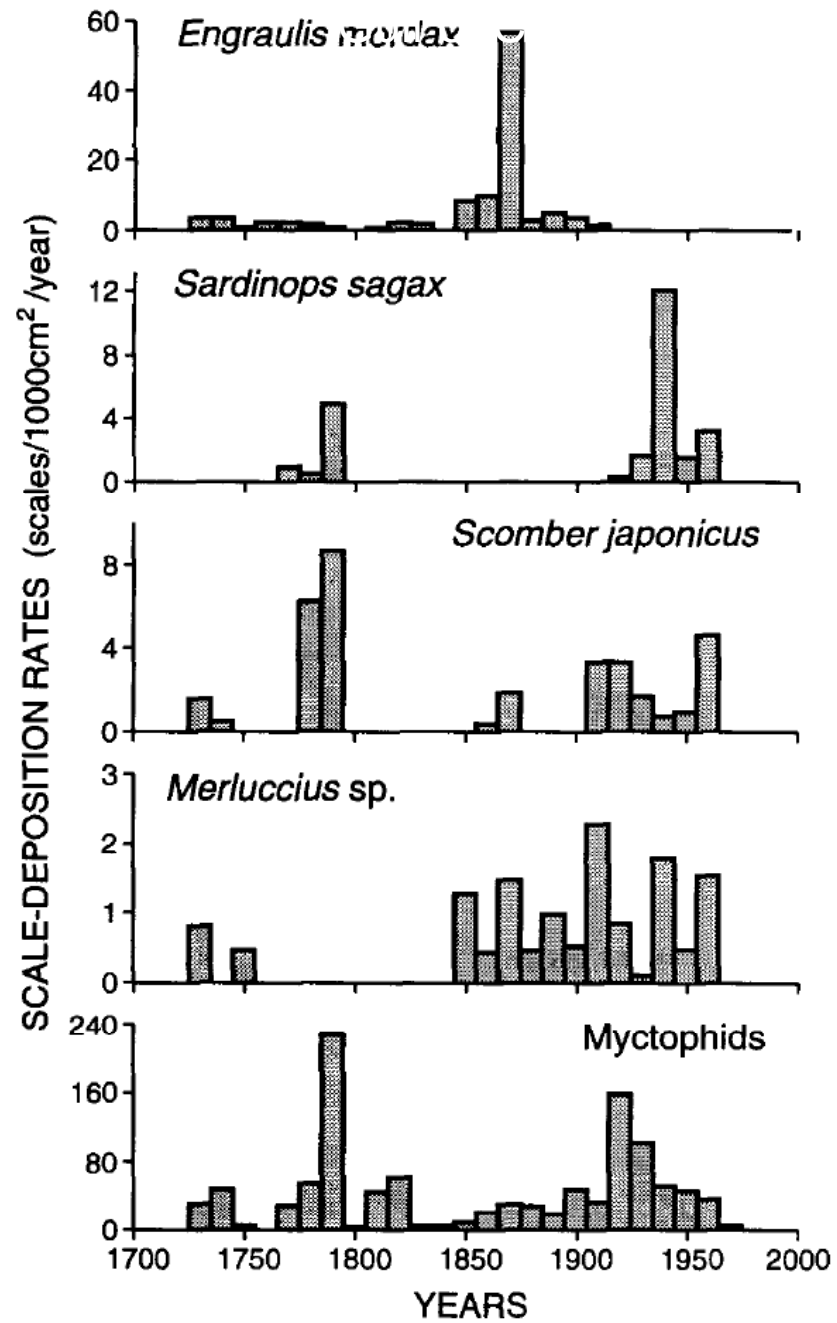
- Much emphasis on climate to fish linkages
 - Global change issues
 - Bottom-up, middle-out, top-down controls
- Perceived inadequacies of single-species approach
- Increasing pressure for ecosystem-based considerations in management
- Continuation of the NEMURO effort
 - Multi-species, individual-based, physics to fish model
 - Proof of principle

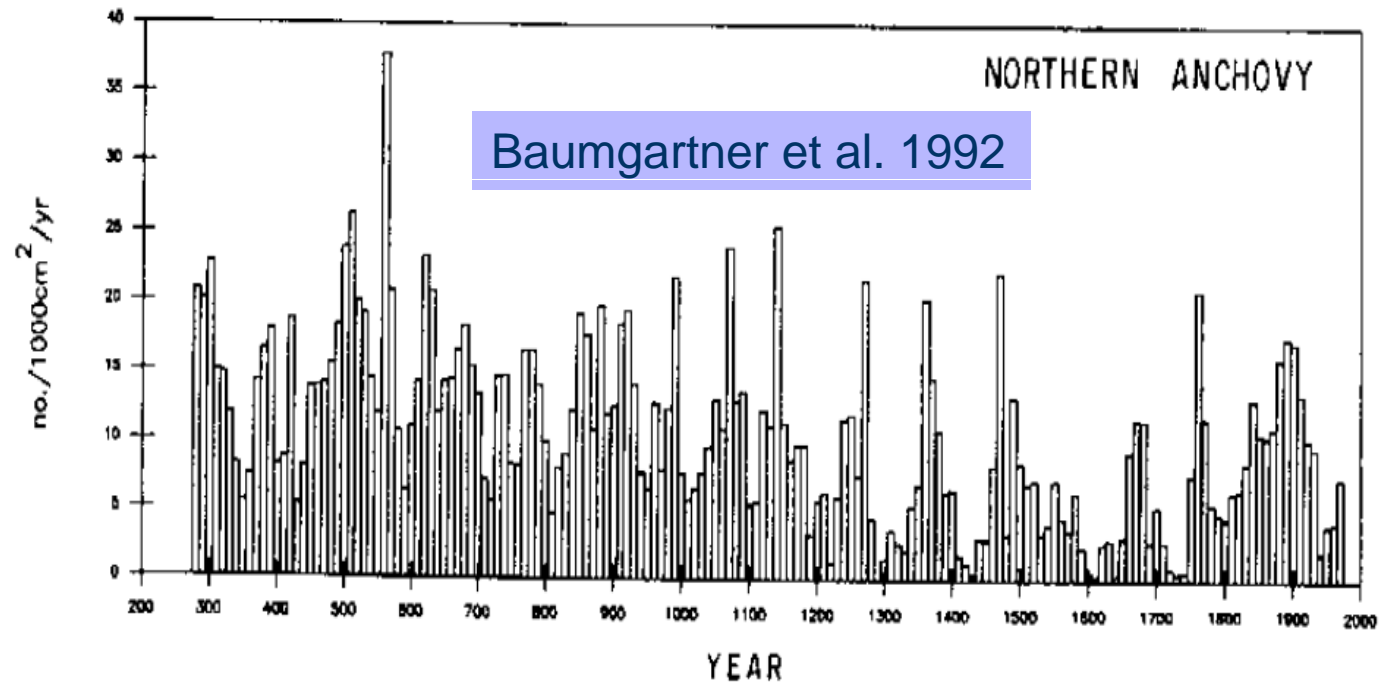
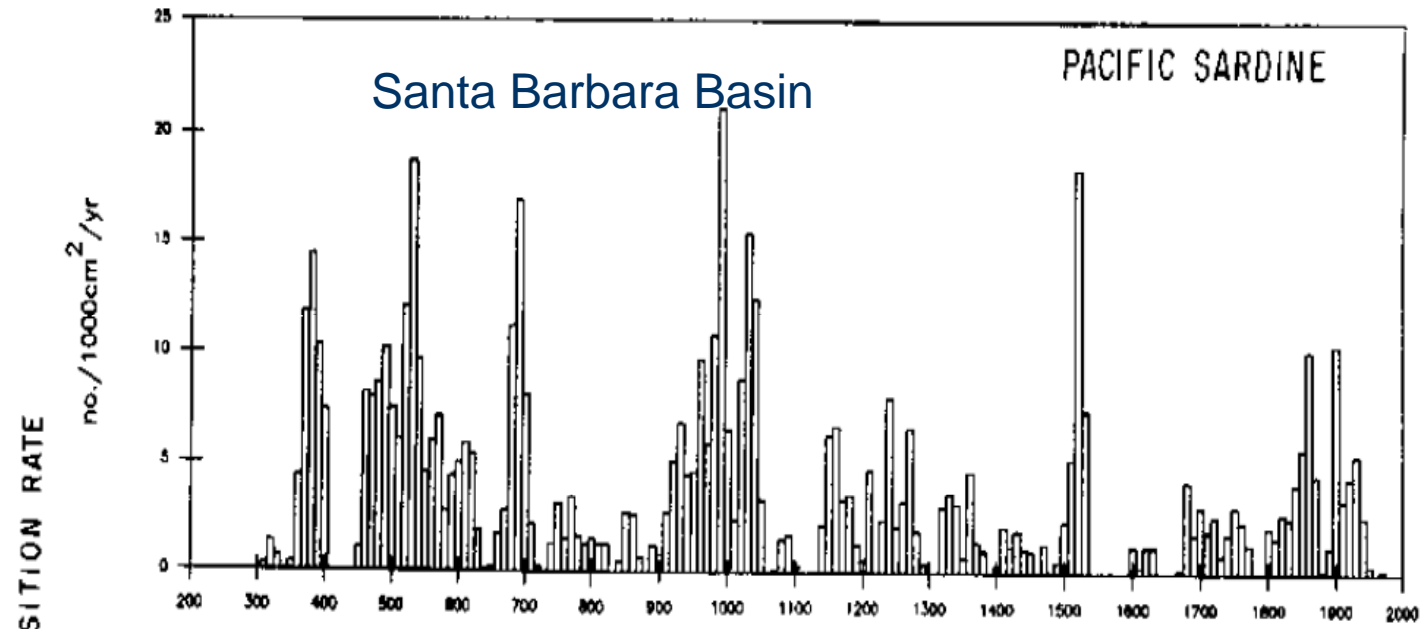
Proof of Principle

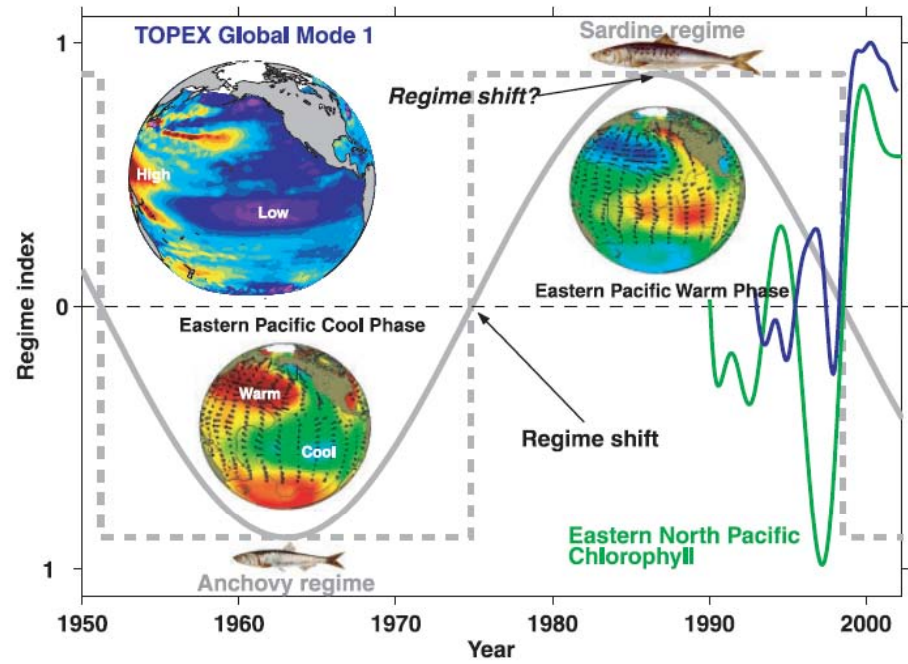
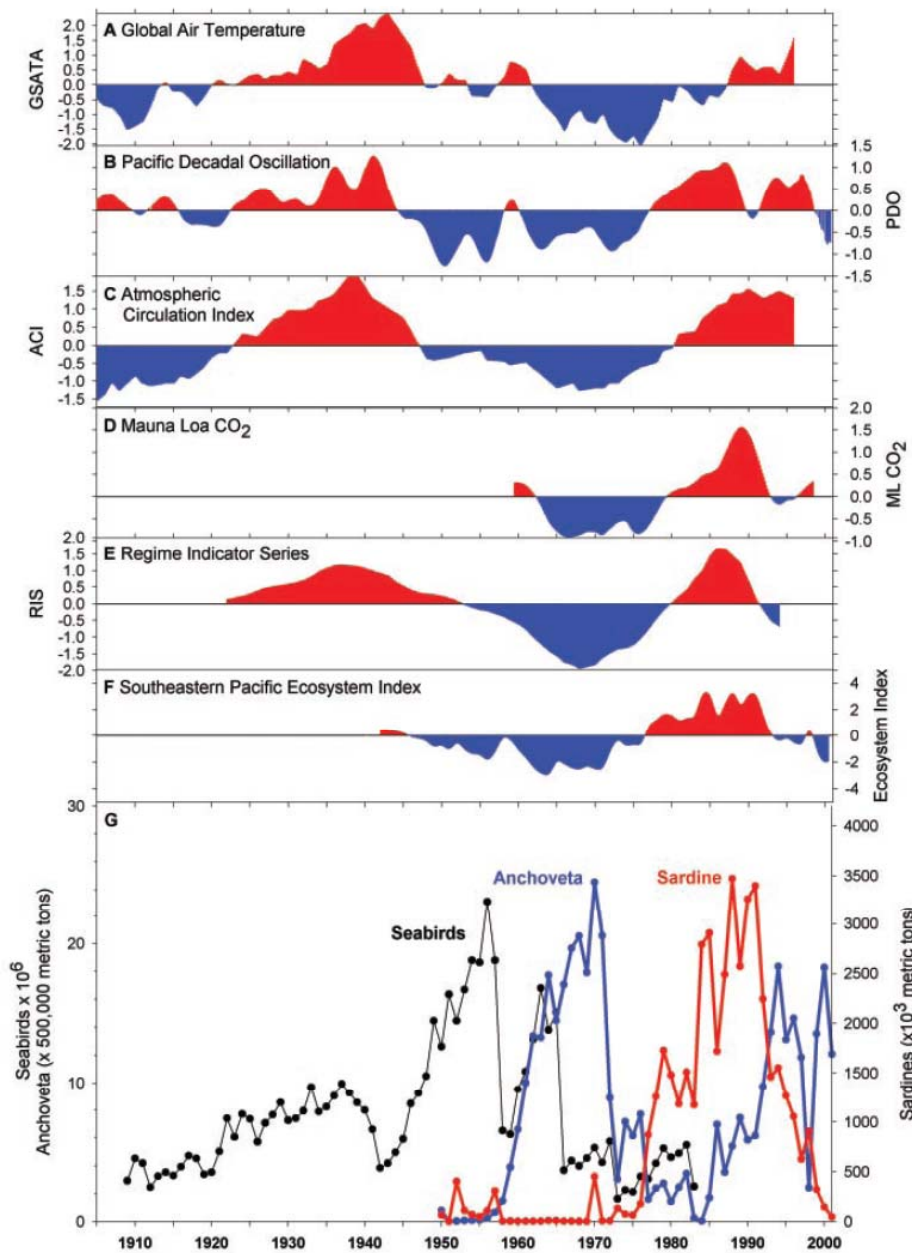
- Sardine – anchovy population cycles
 - well-studied
 - teleconnections across basins
- Good case study
 - Forage fish tightly coupled to NPZ
 - Important ecologically and widely distributed
 - Cycles documented in many systems
 - Recent emphasis on spatial aspects of cycles



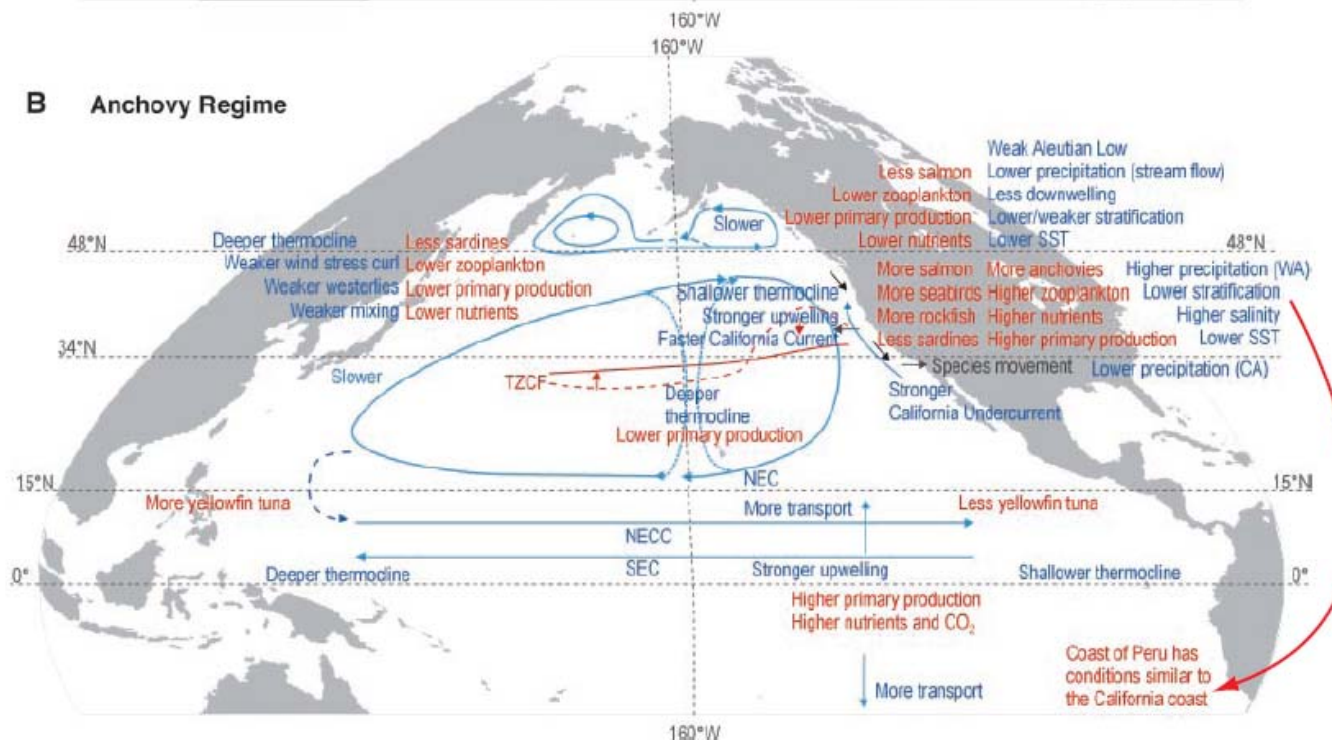
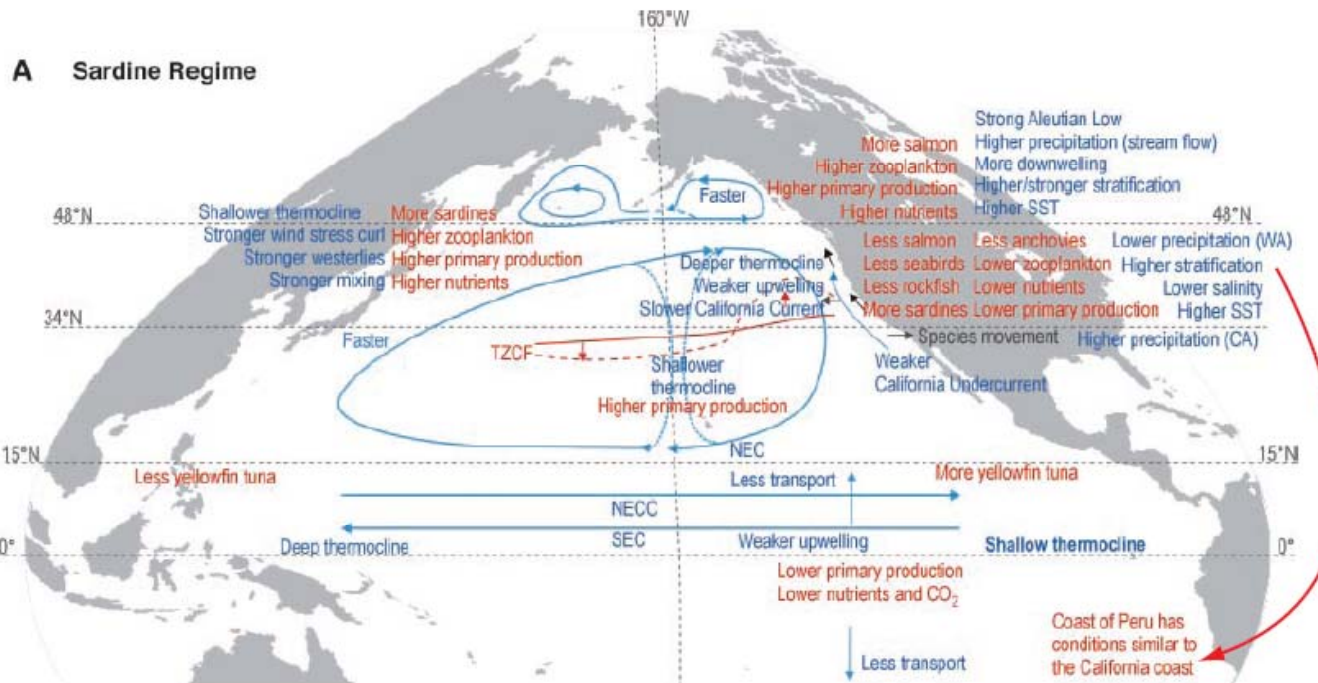
Provided by: Salvador E. Lluch-Cota
 Source: Schwartzlose et al., 1999



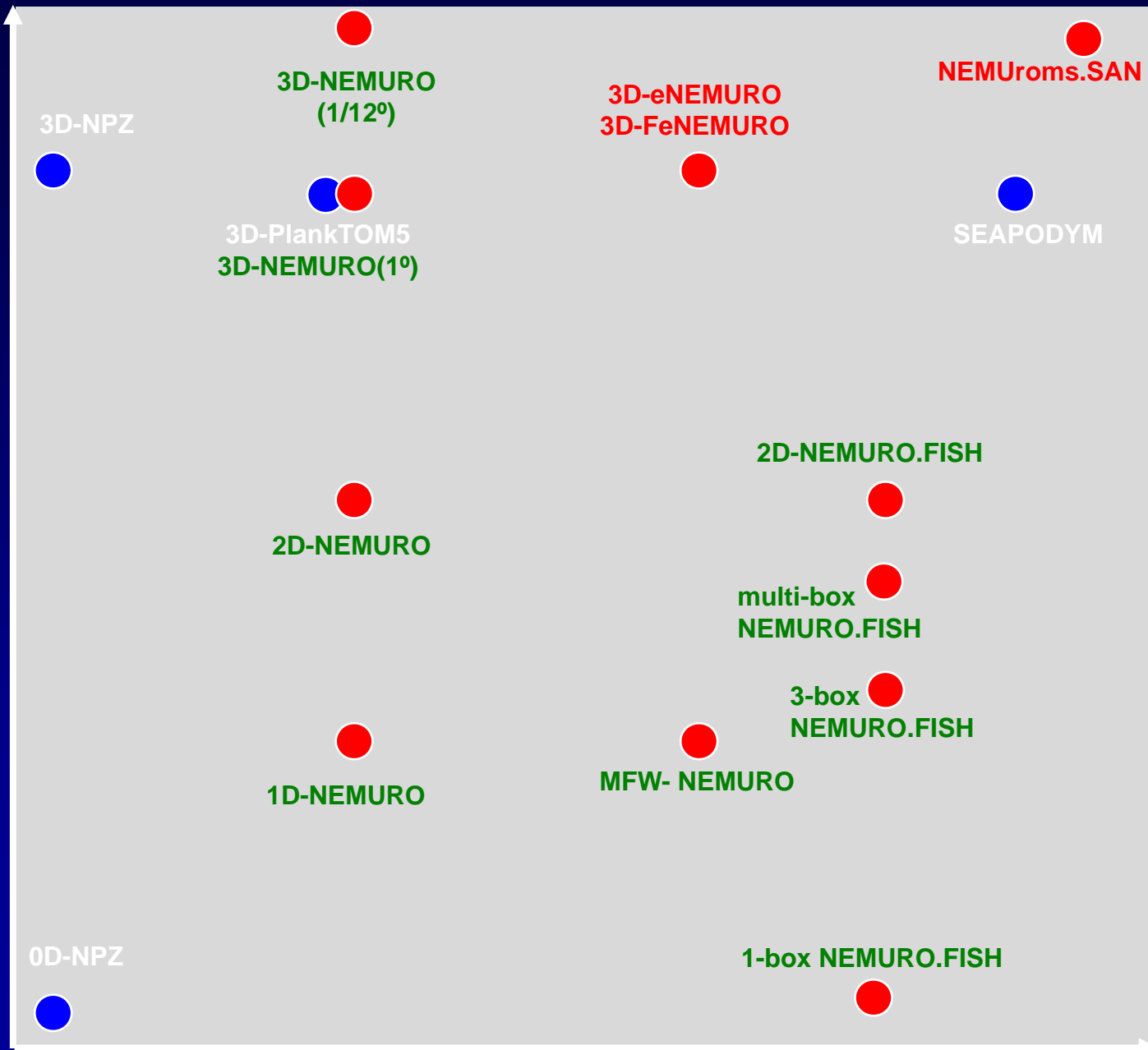




Chavez et al. 2003



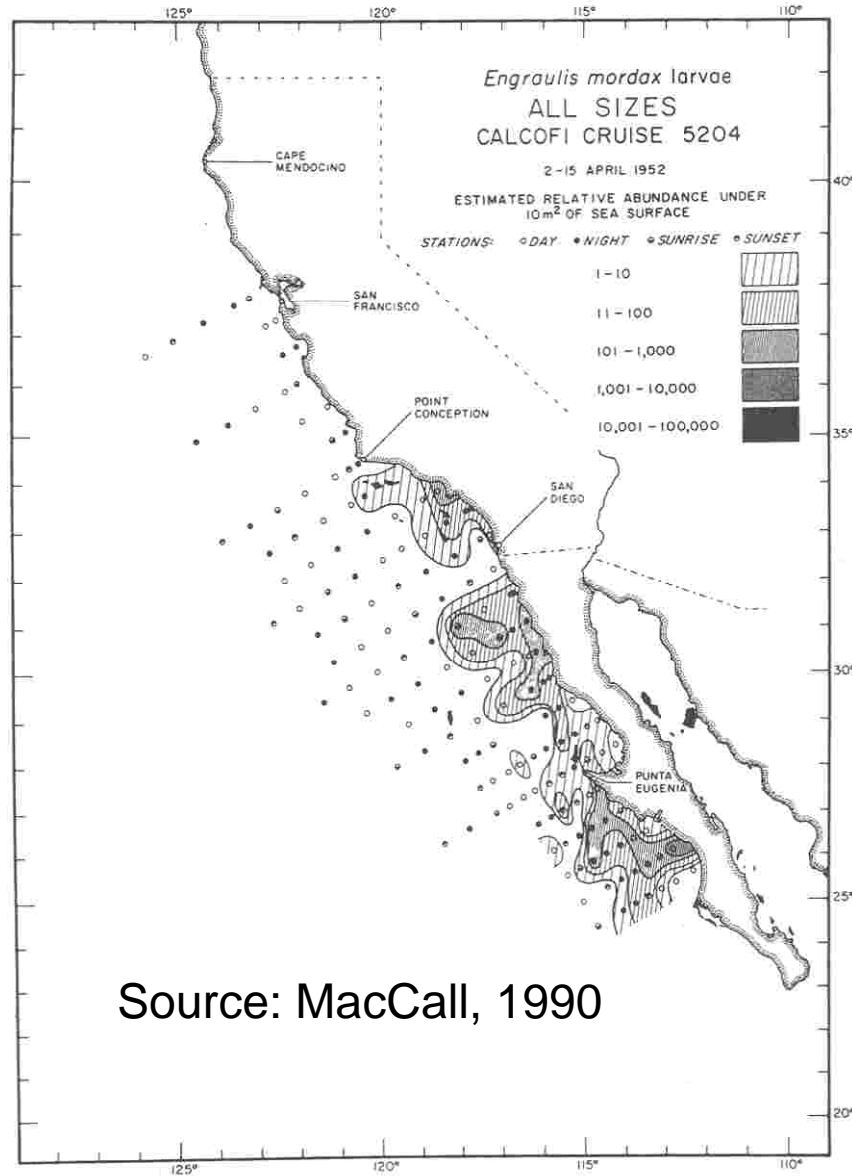
Spatial Resolution



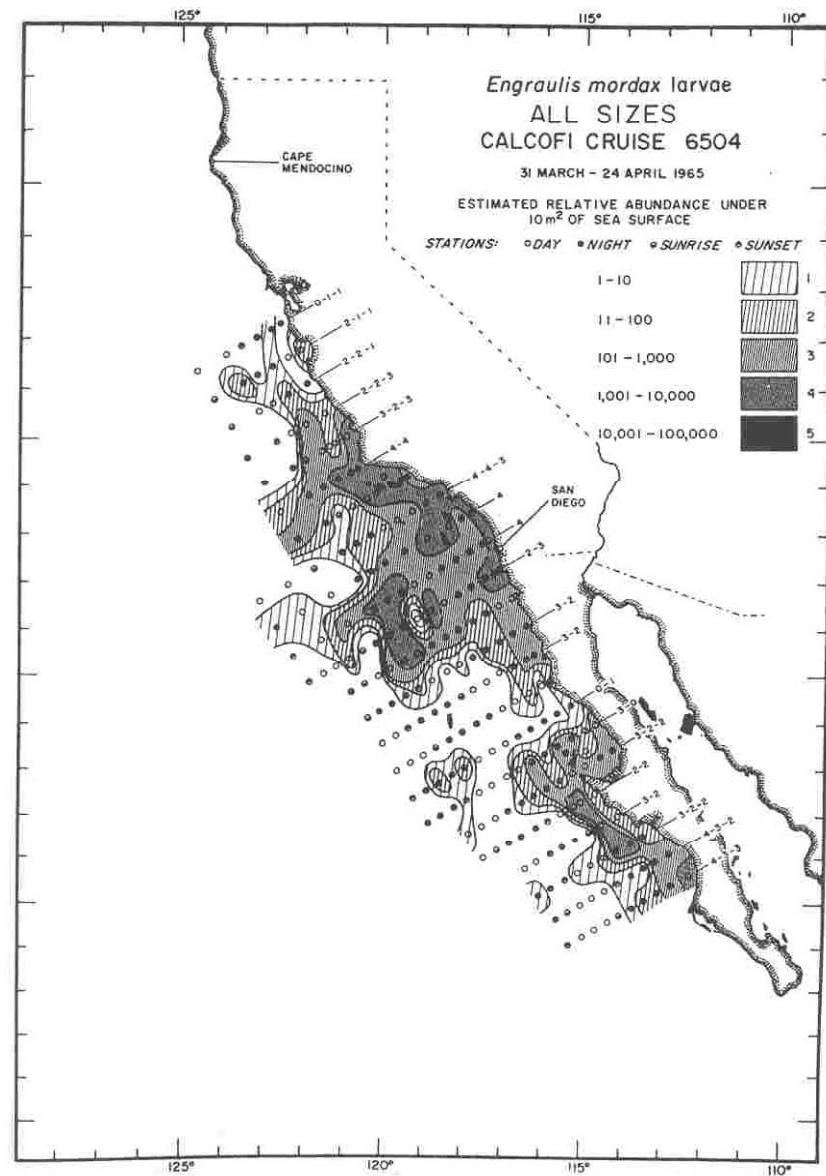
Biological Resolution

Prepared by Shin-ichi Ito

California Current



Source: MacCall, 1990



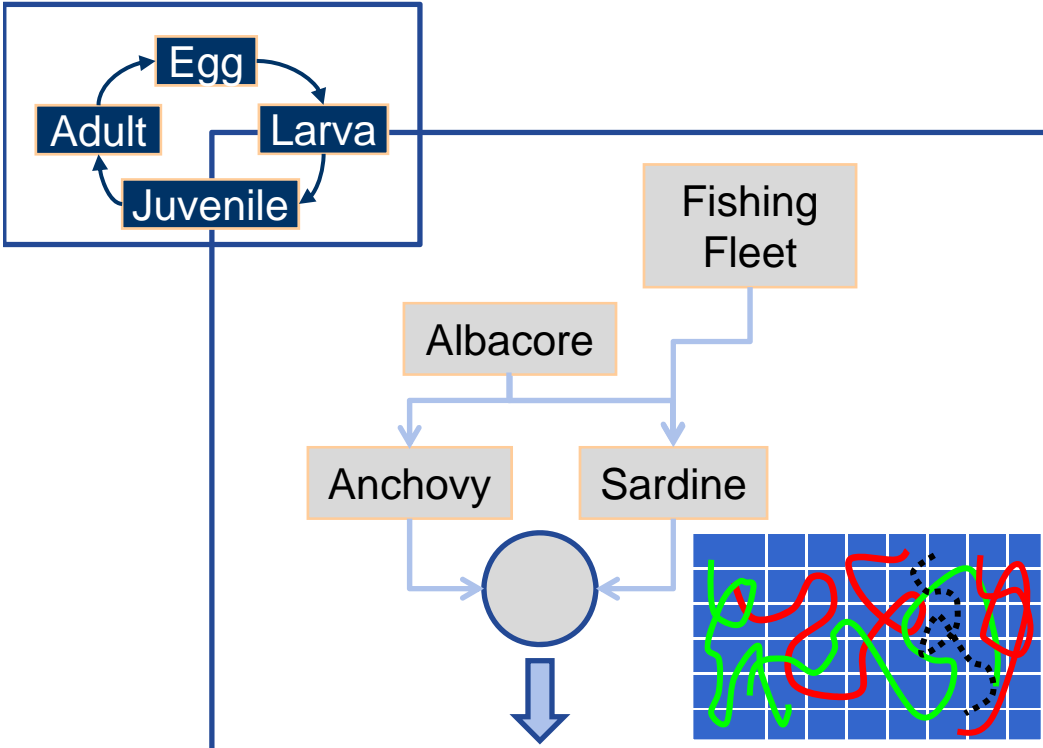


Why IBM for Fish

- Natural unit in nature
- Allows for local interactions and complex systems dynamics
- Complicated life histories
- Experience (memory) is important
- Plasticity and size-based interactions
- Conceptually easier movement

Challenge

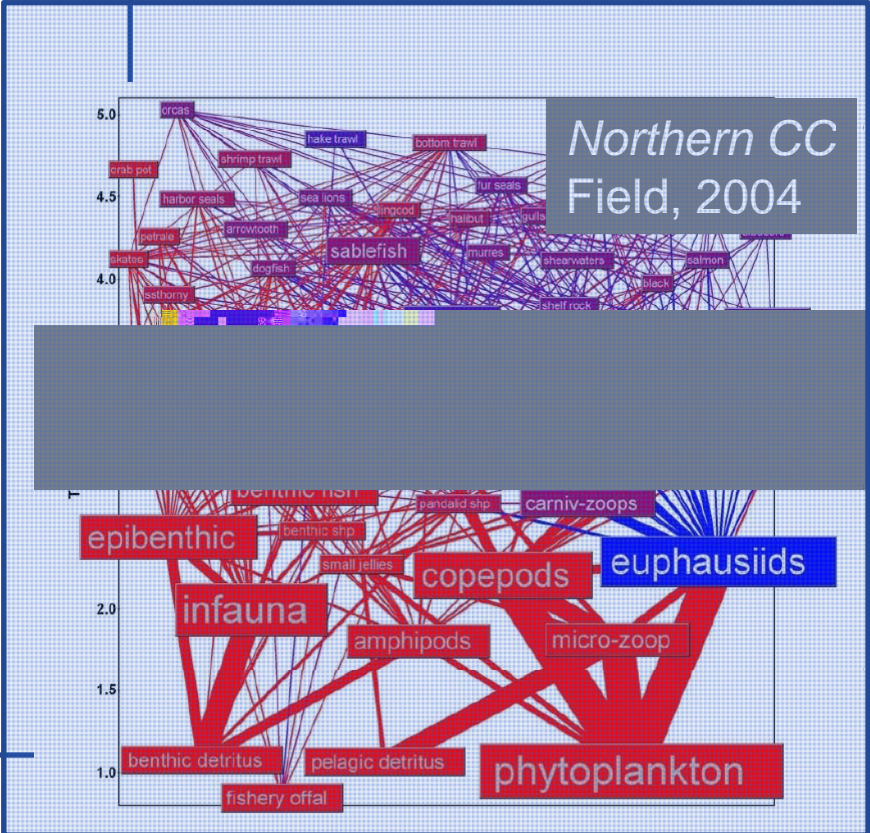
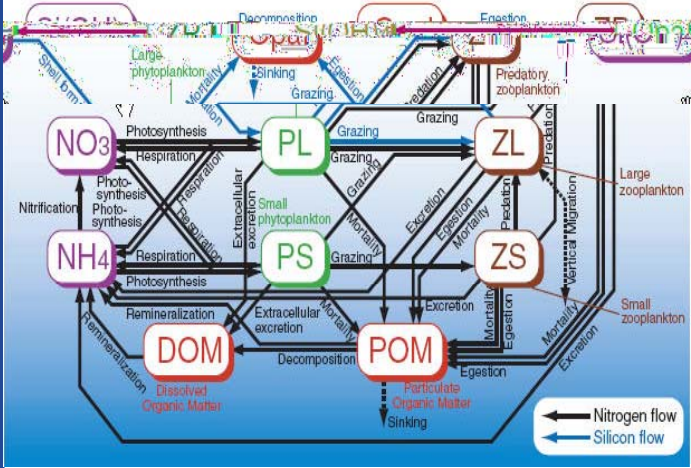
- How to combine models with different temporal and spatial scales
- No general theory
 - Modeling as judgement
- Including human dimensions
- Working across disciplines



Population

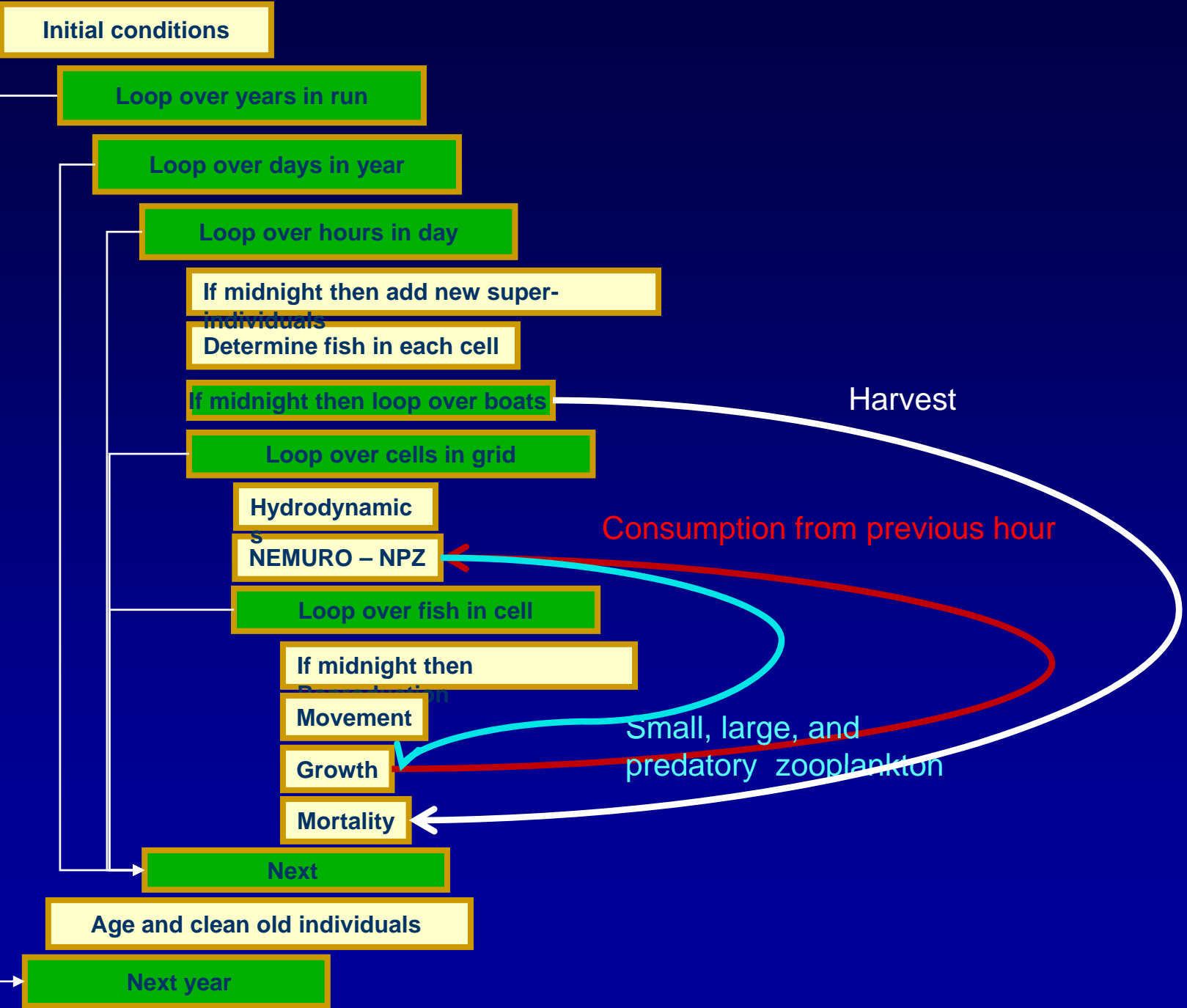
Multi-Species

Food Web/Community



Coupled Models

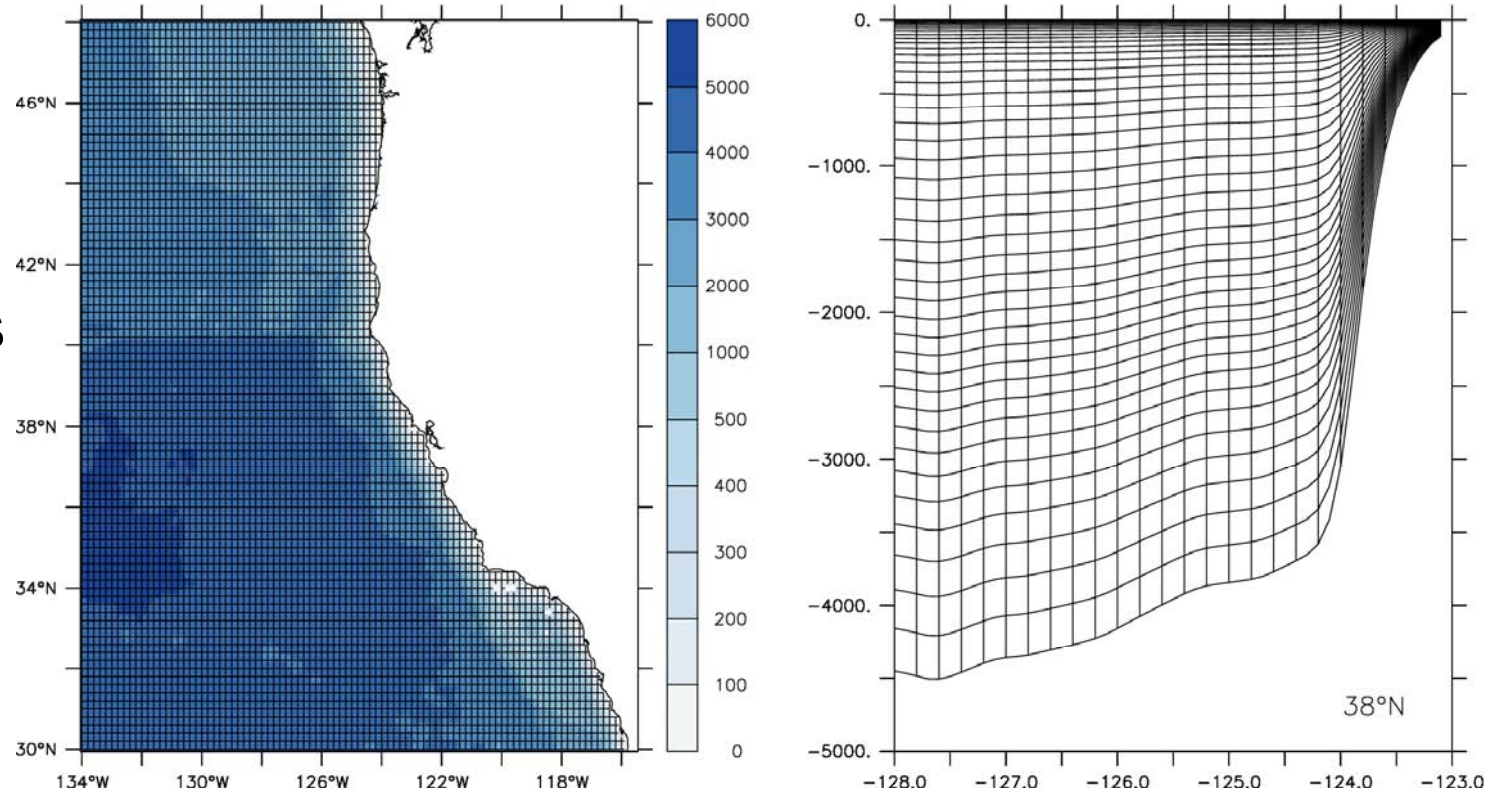
- Model 1: 3-D ROMS for physics
- Model 2: NEMURO for NPZ
- Model 3: Multiple-species IBM for fish
- Model 4: Fishing fleet dynamics
- Today: progress to date
 - Solved many of the numerical and bookkeeping
 - Next is to add realistic biology



Model 1: ROMS

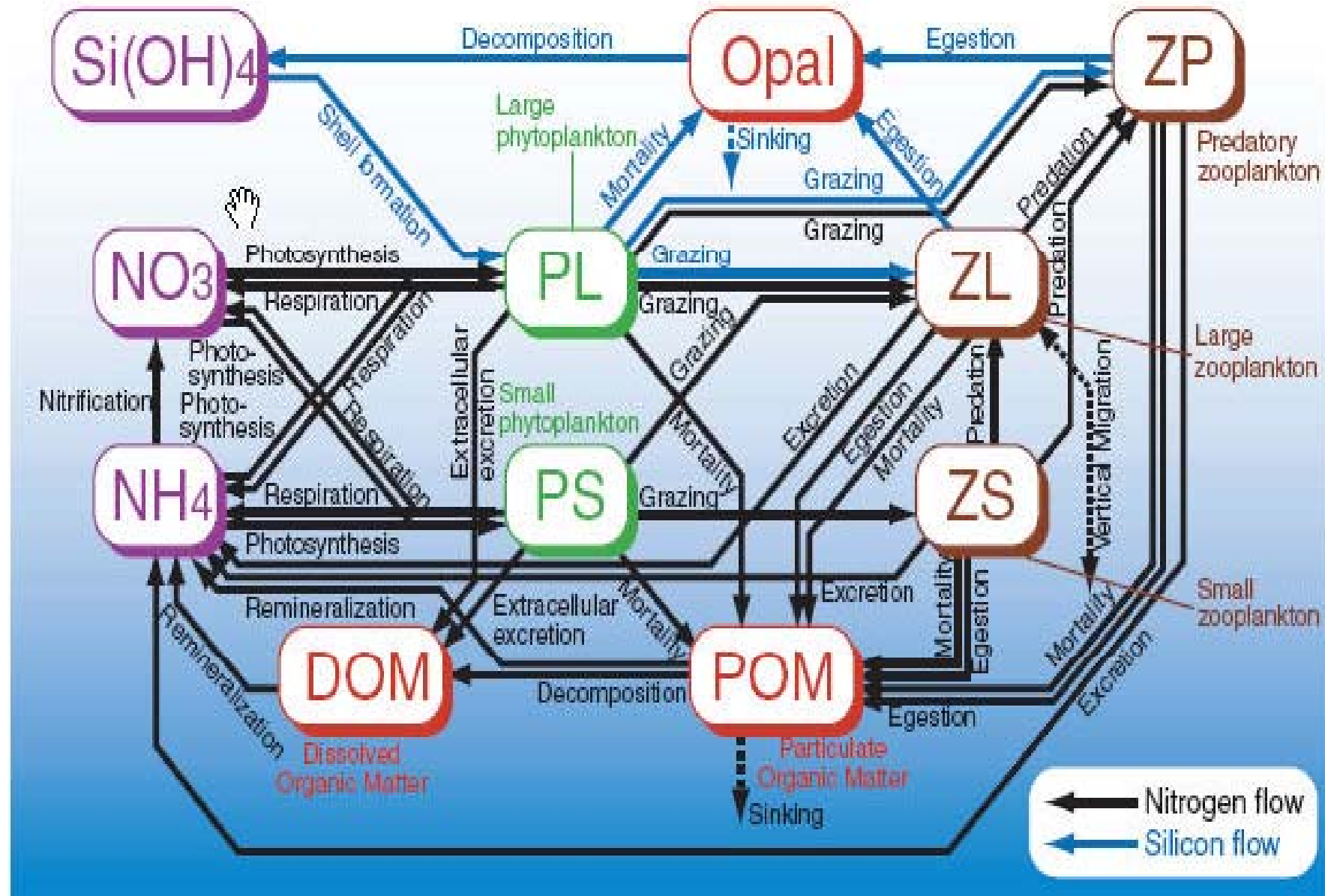
- Grid:
10 km
42 levels

- 900 s



- Run duration: 40 years (1958-2007)

Model 2: NEMURO



Model 3: Fish IBM

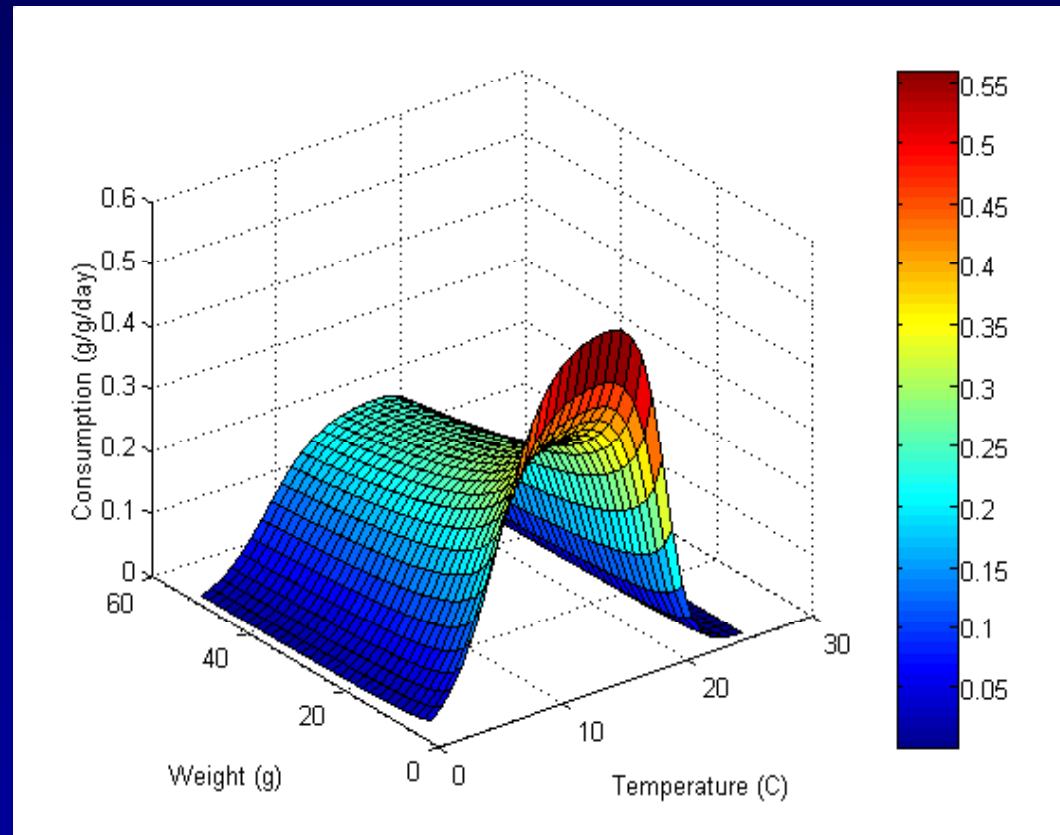
Species Types

- Sardines and anchovy – fully modeled
 - Reproduction, growth, mortality, movement
 - Competitors (food, space) and predators
- Migratory predator
 - Enter and exit the grid
 - Movement and consumption of sardine and anchovy only
 - “albacore”

Fish IBM: Full members

- Life cycle framework
 - Easy to say, creates bookkeeping challenge
 - Cannot keep adding new fish to the model
- Vital processes:
 - Growth ← ROMS temp and NEMURO zoopl
 - Development ← ROMS temp
 - Reproduction ← ROMS temp
 - Mortality ← constant, starvation, predation, fishing
 - Movement ← ROMS transport and temp; kinesis

$$W_{t+\Delta t} = W_t + [(A \cdot C - R) \cdot W_t \cdot \left(\frac{e_f}{e_z} \right) - \frac{E}{e_f}] \cdot \frac{\Delta t}{86400}$$



E was computed as J/day based on whether a batch was produced at midnight

Condition and projected J needed for a batch

Batch developed based on temperature

Resting period

Fish IBM: Mortality

- Fish eating fish
 - Individual albacore eating individual fish
- Natural (background)
- Harvest of sardine
 - Individual fishing boats
- $Worth_{i,t+1} = Worth_{i,t} e^{-\sum M_i}$

Movement

- A major challenge is modeling movement
 - Eggs and larvae maybe reasonably simulated with particle-tracking
 - Juveniles and adults require behavioral approaches
- Wide range of temporal and spatial scales
 - Often scales determined by other submodels
 - Compatibility issues

Movement

- Many approaches have been proposed
 - $X(t+1) = X(t) + V_x(t) * \Delta t$
 - $Y(t+1) = Y(t) + V_y(t) * \Delta t$
 - $Z(t+1) = Z(t) + V_z(t) * \Delta t$
 - Determine the cell



Fish IBM: Movement

- Eggs, yolk-sac, and larvae move by physics
 - assumed at surface for now
- Juveniles and adults move by behavior
 - Day-to-day
 - Seasonal migrations
- Each individual has a continuous x, y, and z position
- Position mapped to 3-D grid every 900 sec to determine cell location and local conditions

Kinesis Movement

(Humston et al. 2004)

- X and Y velocities of each individual is computed daily and applied every 900 sec

- Kinesis behavior (response to temperature and food)

$$V_x = I_x + R_x$$

$$V_y = I_y + R_y$$

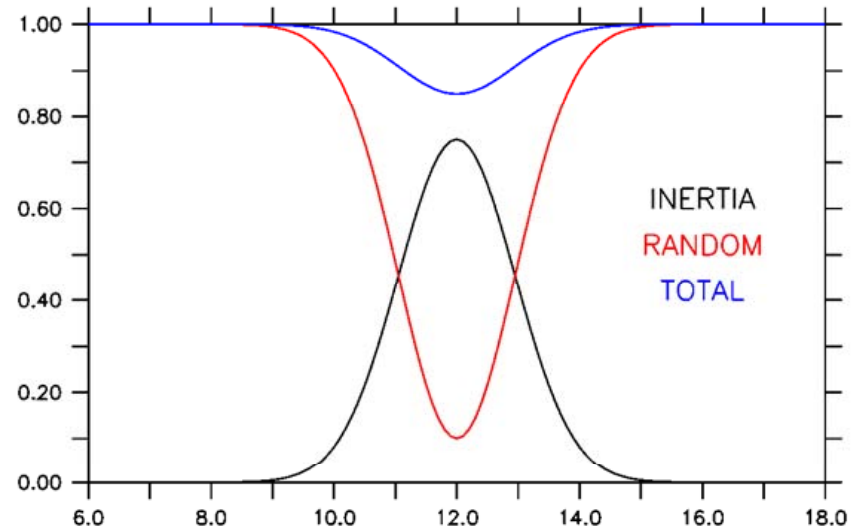
$$V_z = I_z + R_z$$

- Kinesis is the sum of random (R) and inertial (I) velocities (happiness)

Fish IBM: Kinesis Movement

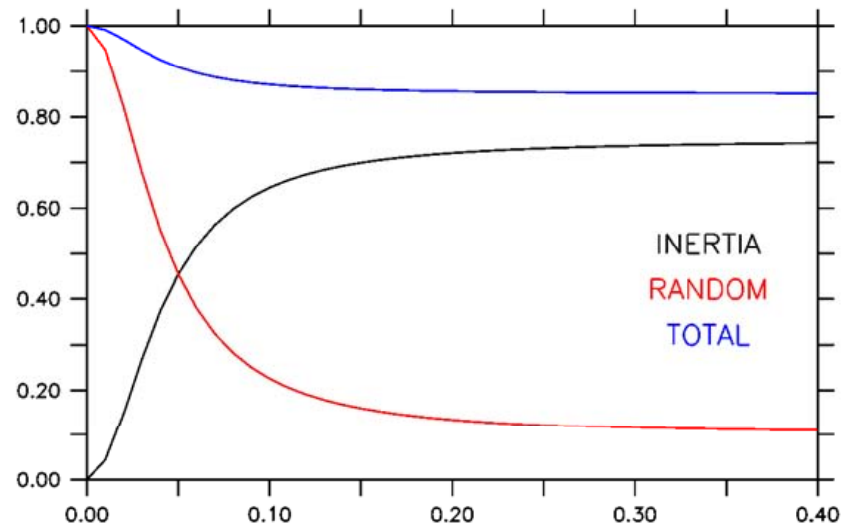
- Inertial:

$$I_x = V_x(t-1) \times f(TorP)$$



- Random:

$$R_x = r \times g(TorP)$$



Model 4: Fishing Fleet

- 100 boats and 5 ports - sardine
- Day boats so complete a trip in 24 hours
- Daily evaluation
- Compute expected net revenue (ENR) based on:
 - Perceived CPUE (10-day average)
 - Price per pound
 - Cost per km
 - Return to nearest port

Numerical Details

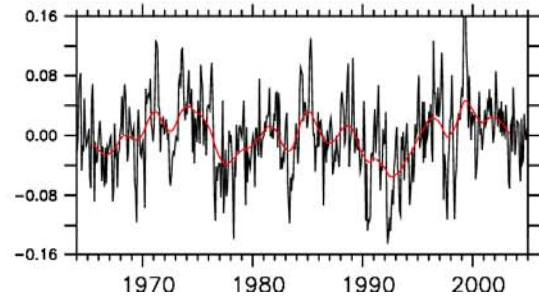
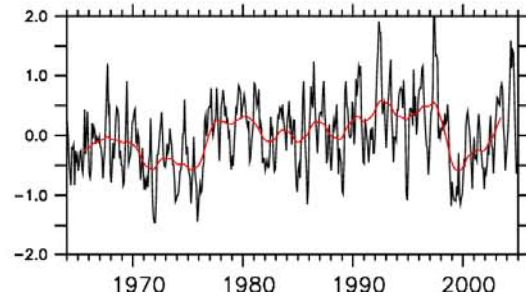
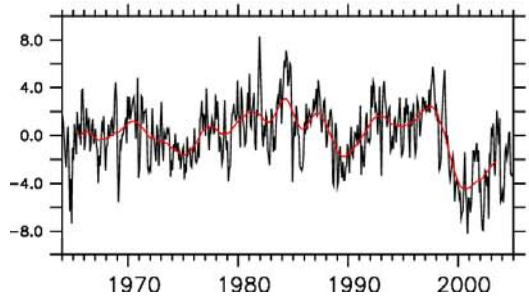
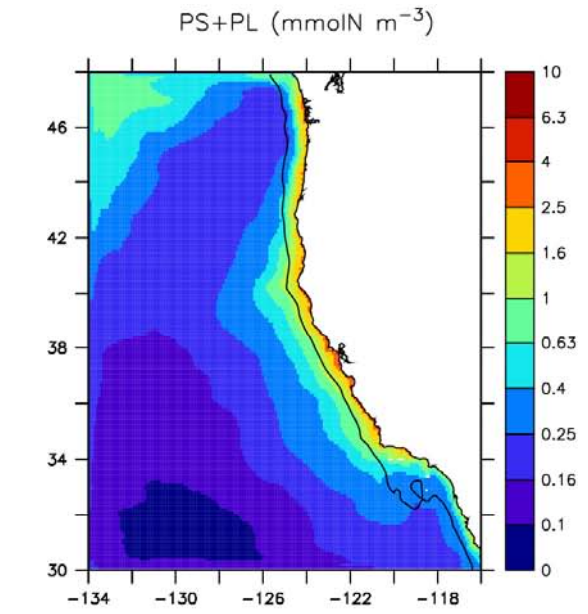
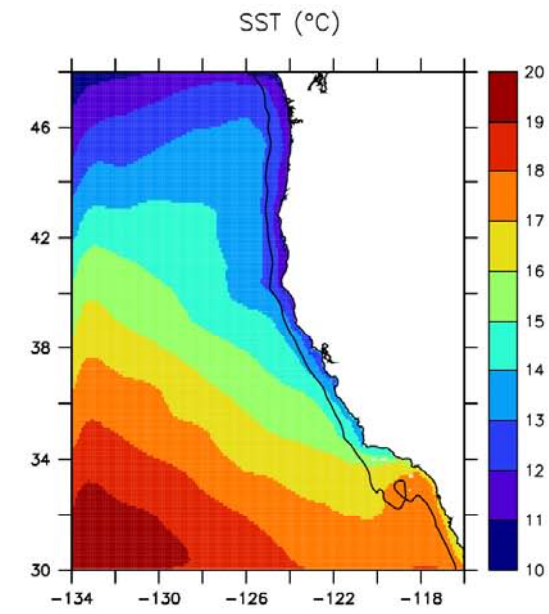
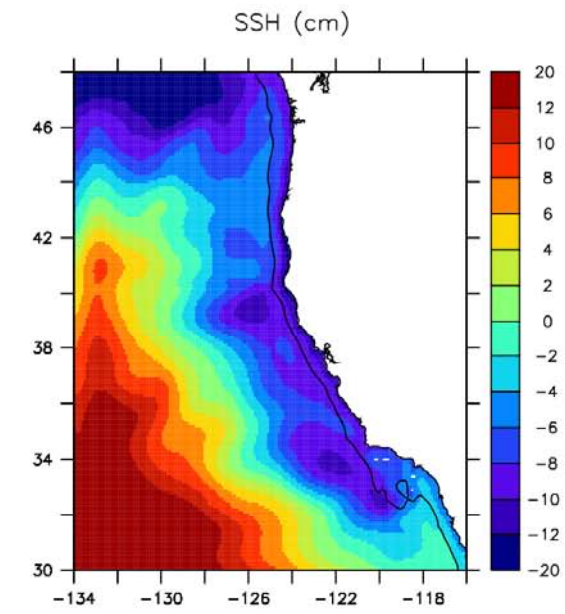
- Major numerical and bookkeeping challenges
- Solving everything simultaneously
 - Two-way coupling between fish and zooplankton
- We are working within ROMS source code, using the available particle tracking features

Numerical Details

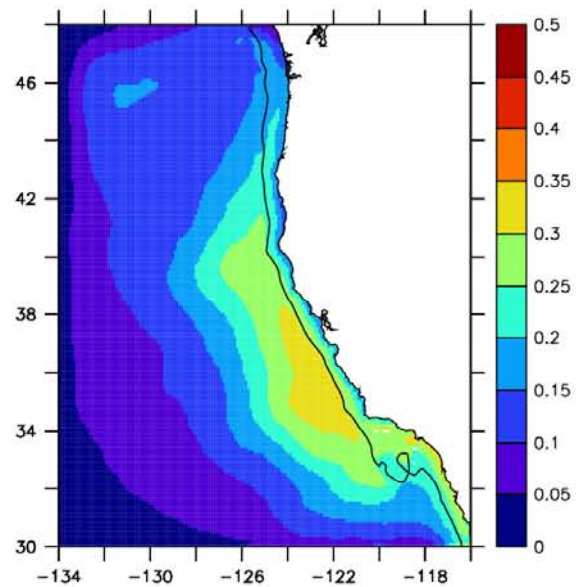
- Computing speed, mass balance, Eulerian with Lagrangian, and full life cycle
 - Interpolate zooplankton fields - correct removal
 - “halo” computing for albacore to eat fish on different processor
 - Super-individual approach (adult produce young who become adults)
- Code is thousands of lines

Model Simulations

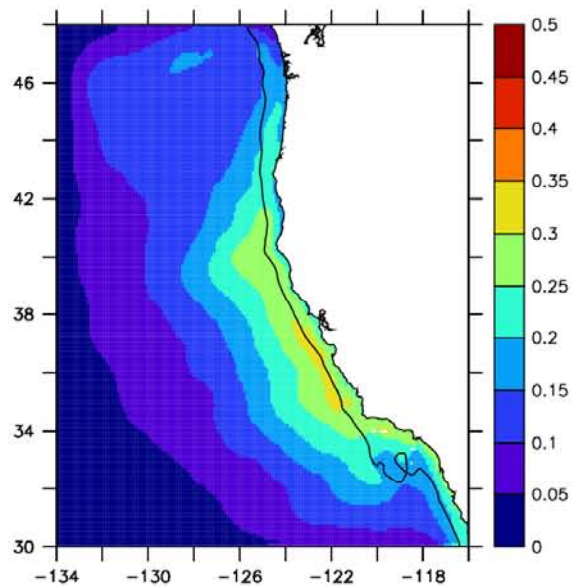
- Fully coupled model
- 1958 to 2007
- Parallel computing (MPI)
 - UC Shared Research Computing Services (ShaRCS) - Berkeley
 - 128 CPUs (Xeon 2.4 GHz, 272 nodes, 8 cores/node, 3 GB/core)
 - 40-year run with 20,000 super-individuals takes ~2 days
 - NCAR BigBlue, DOE Artic Computing Center; Earth Simulator



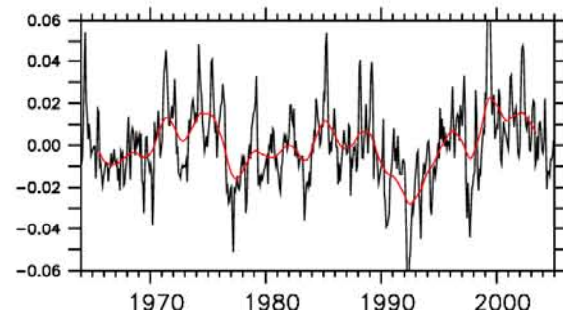
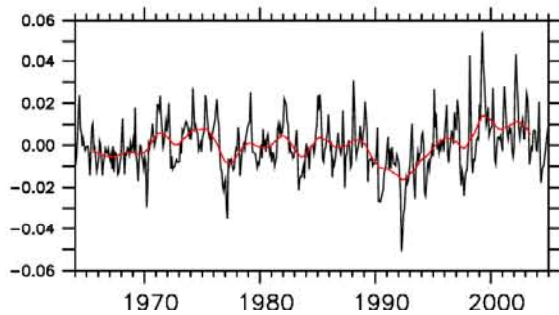
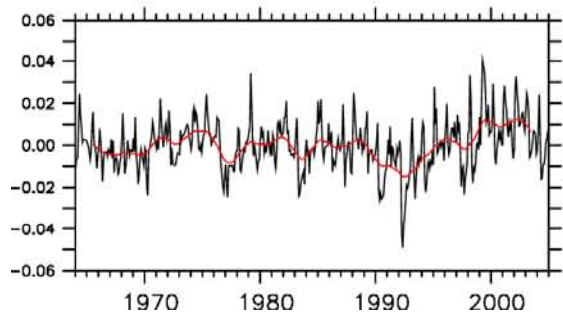
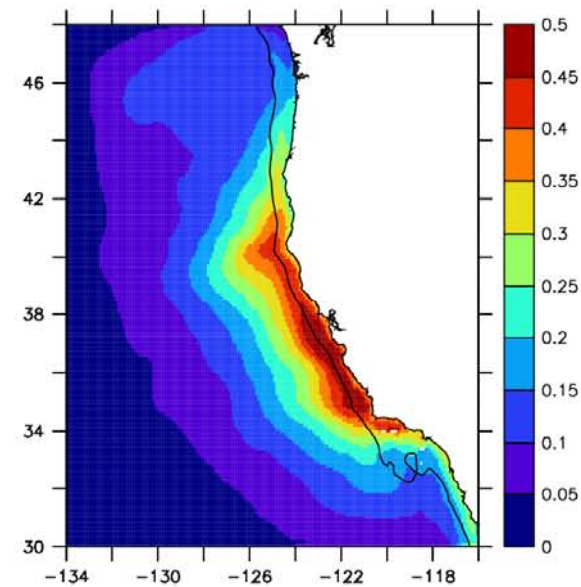
ZS (mmolN m⁻³)



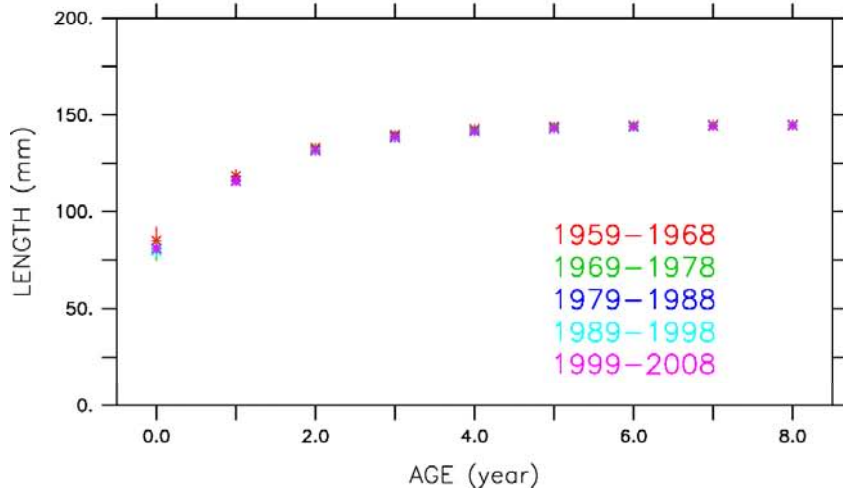
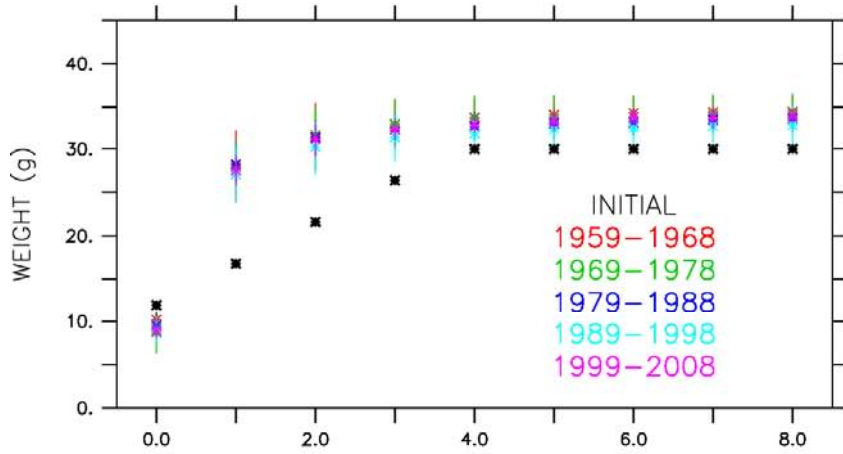
ZL (mmolN m⁻³)



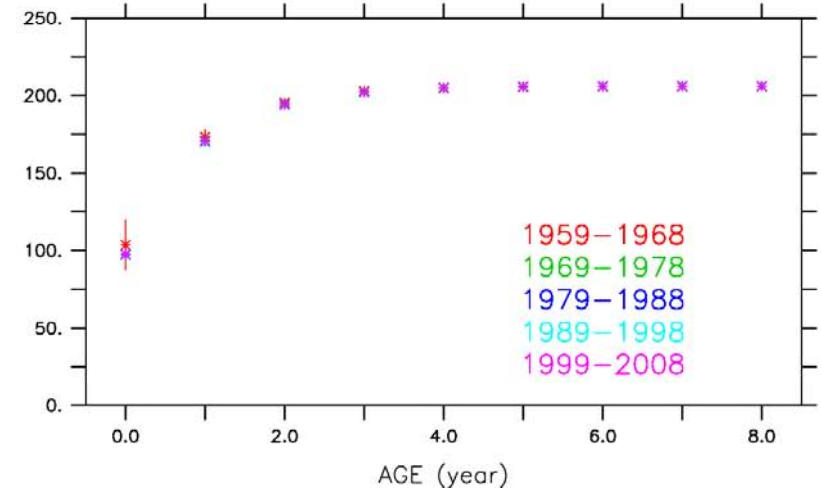
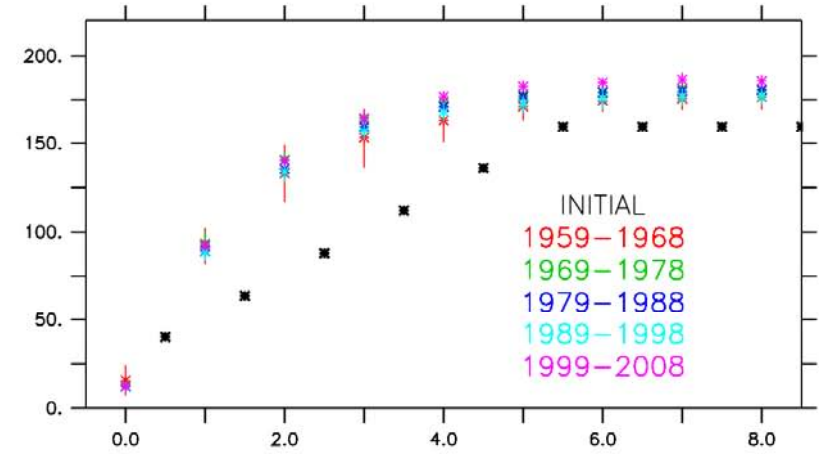
ZP (mmolN m⁻³)

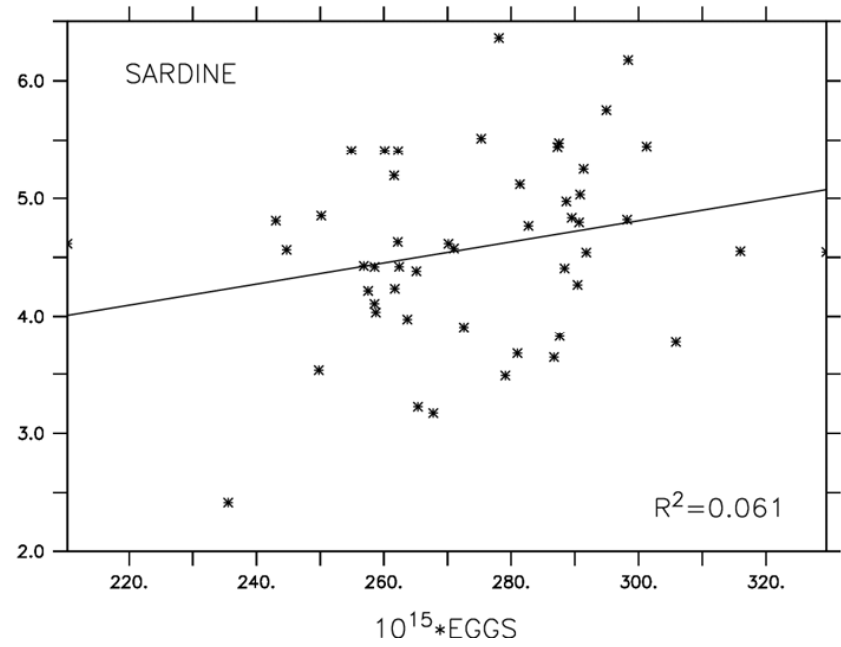
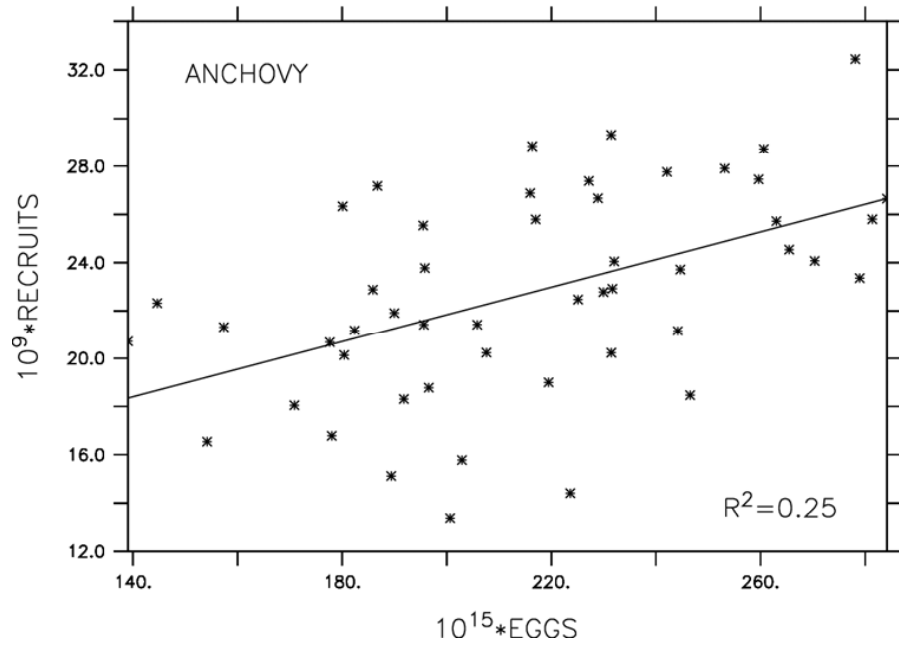
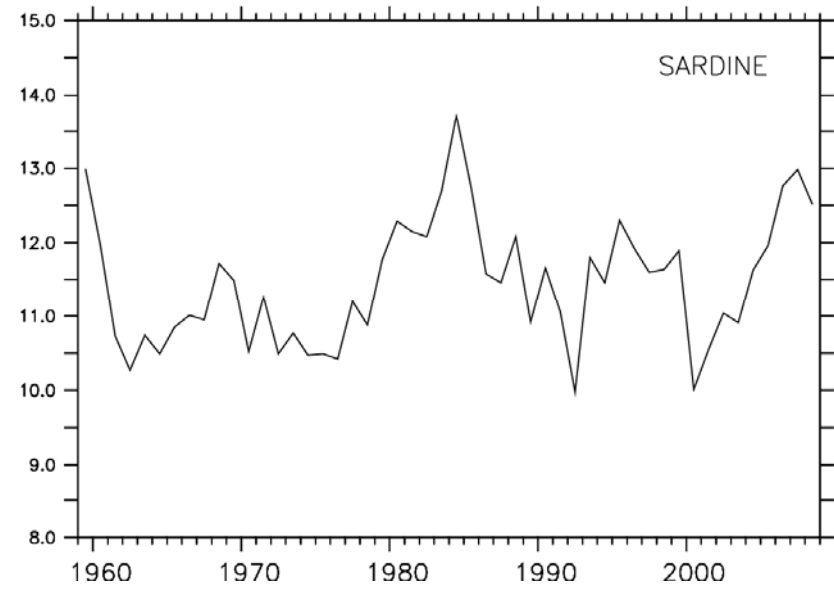
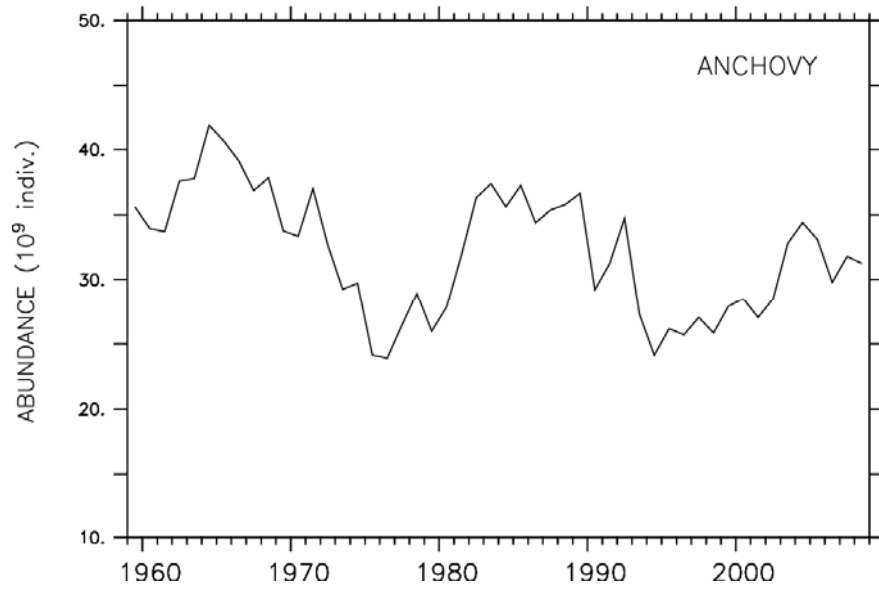


ANCHOVY

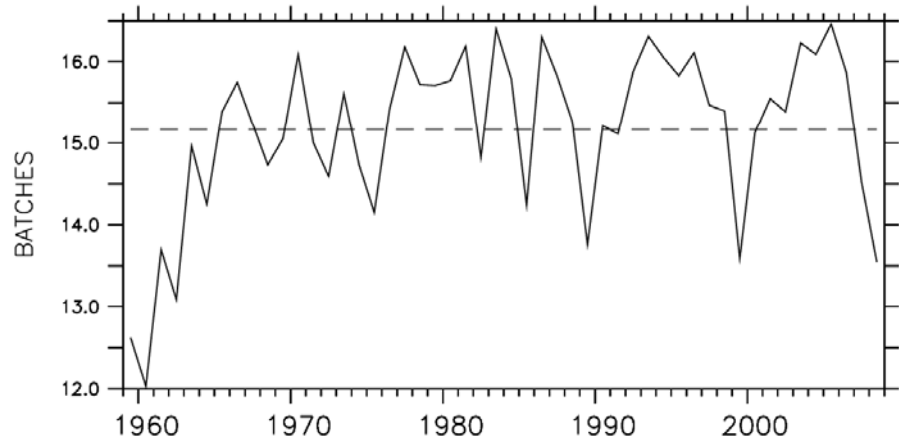


SARDINE

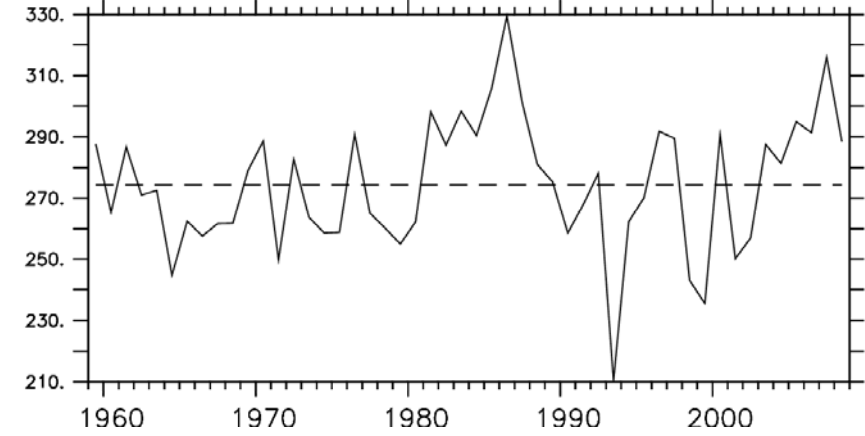
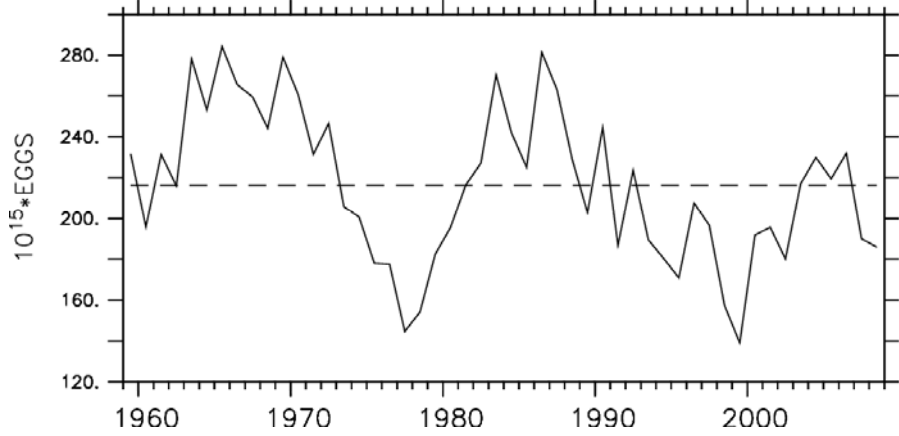
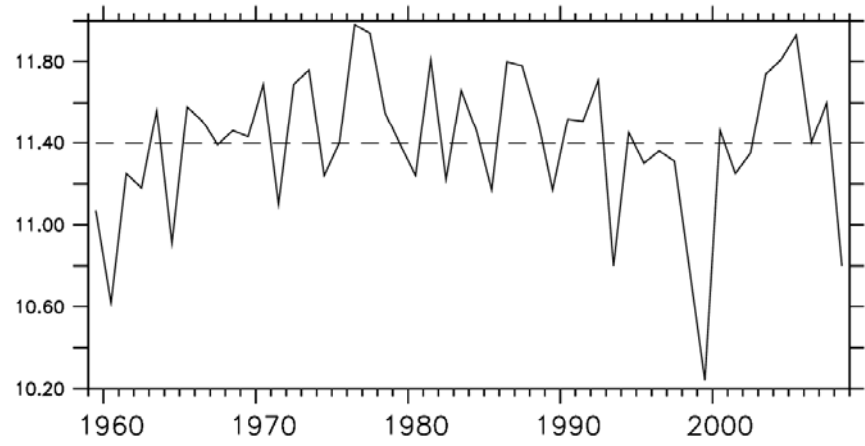


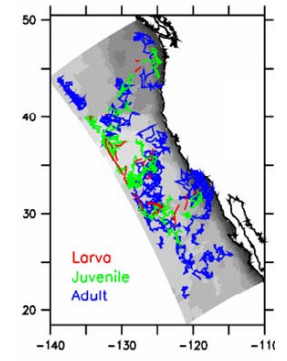
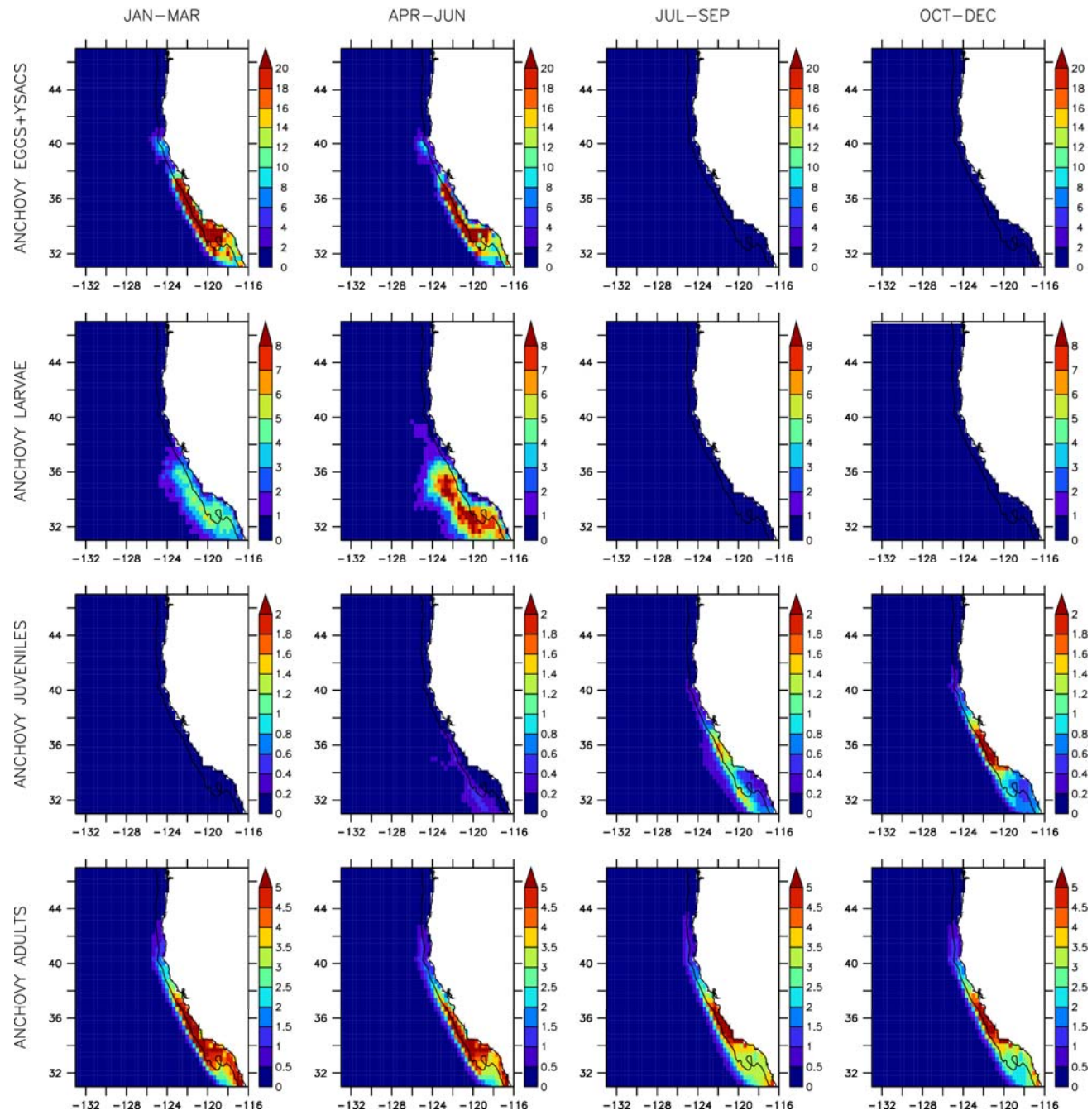


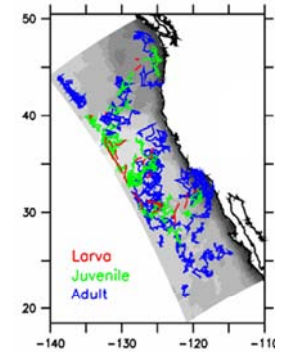
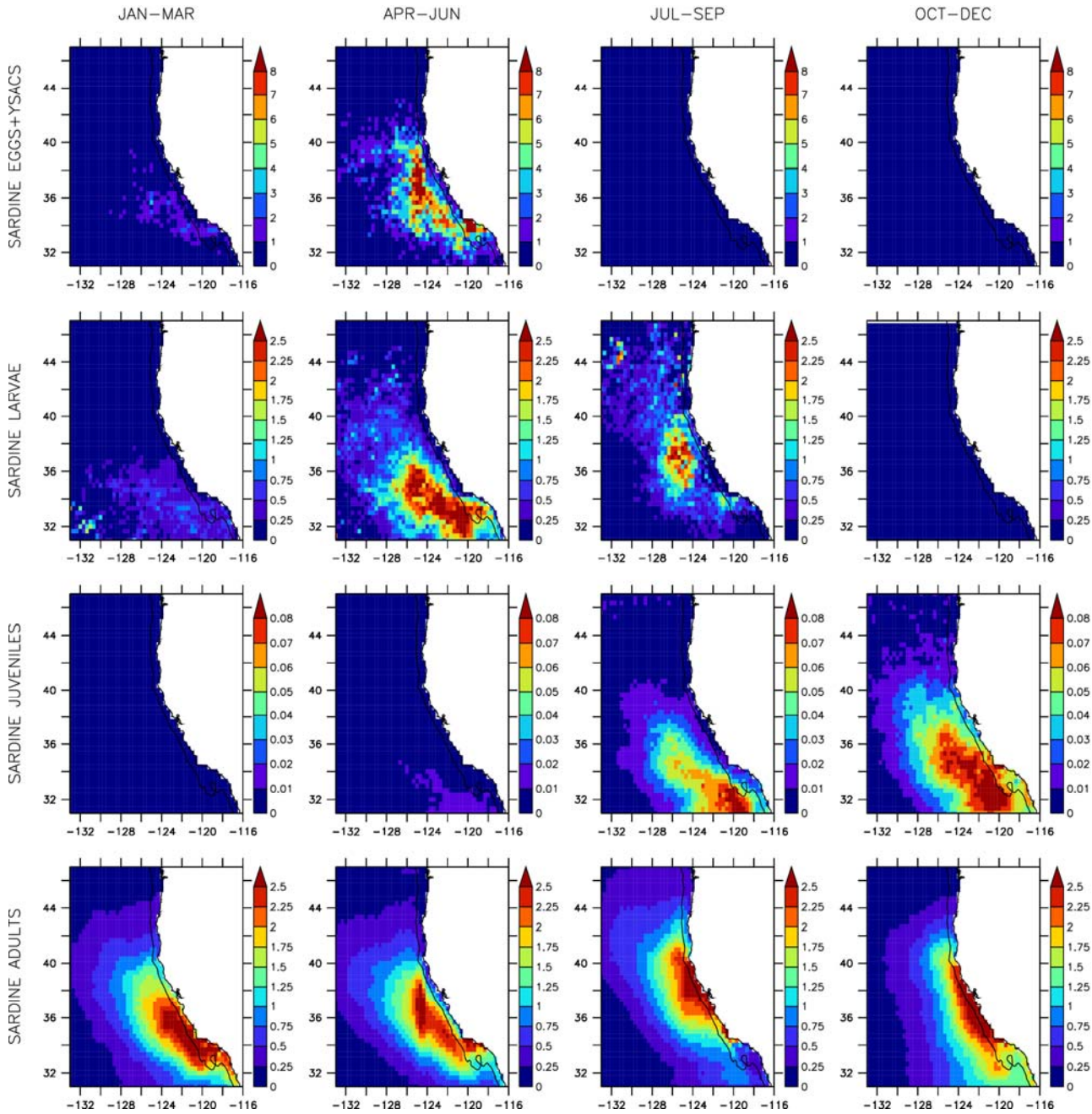
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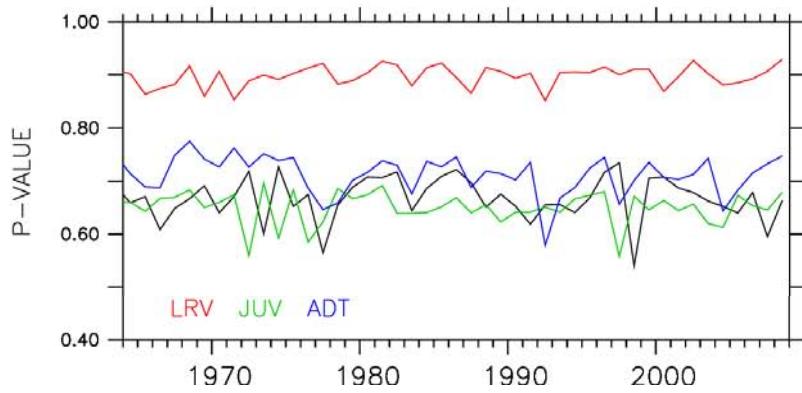
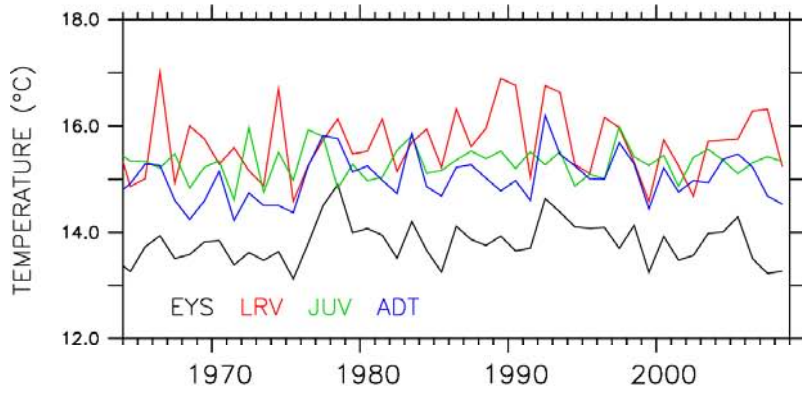
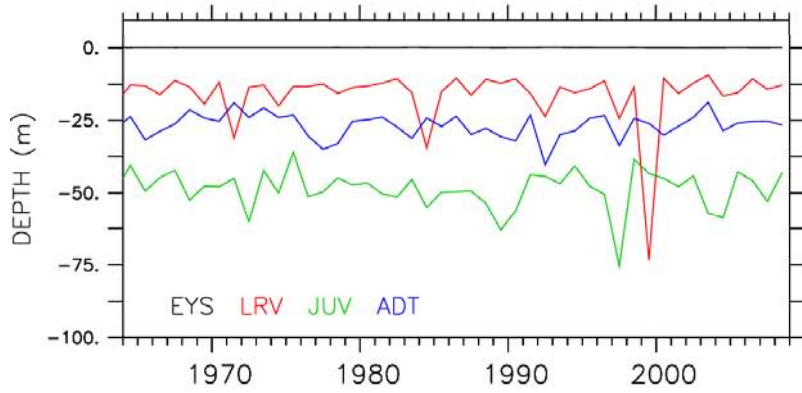
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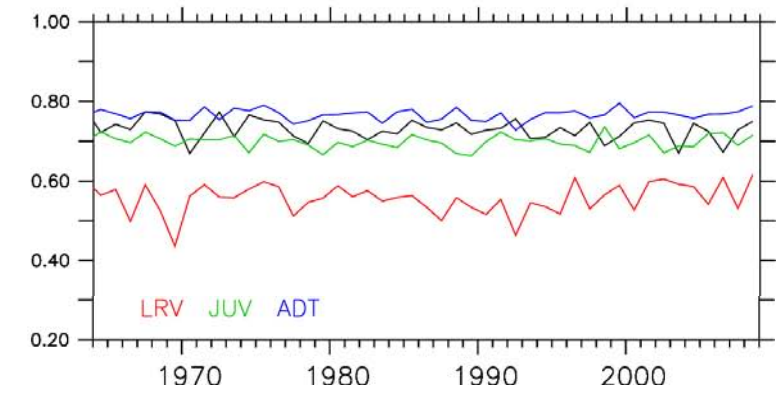
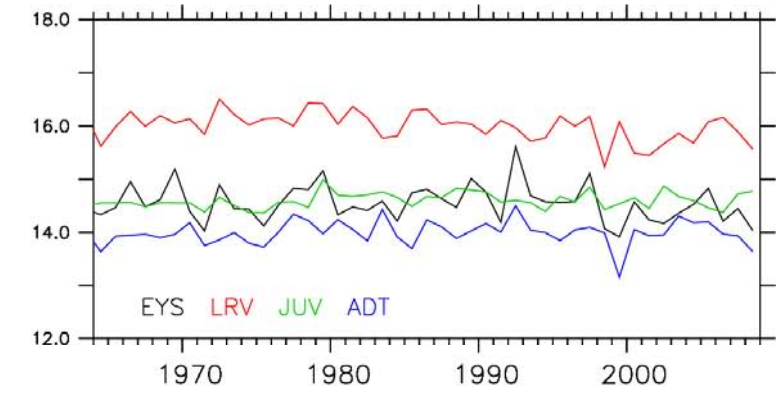
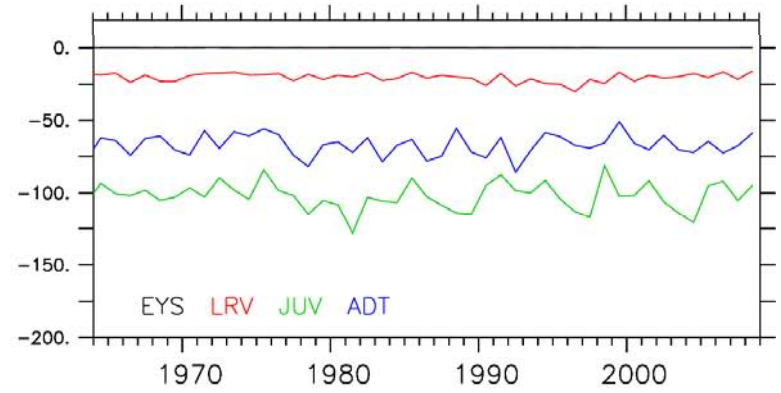


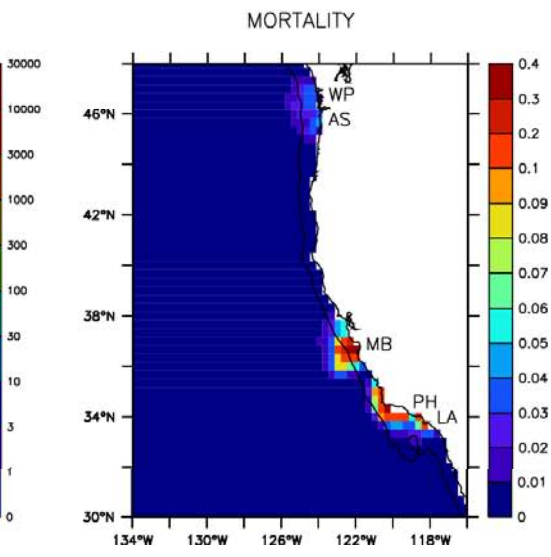
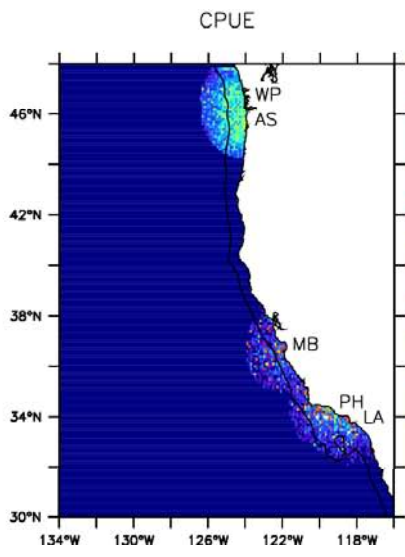
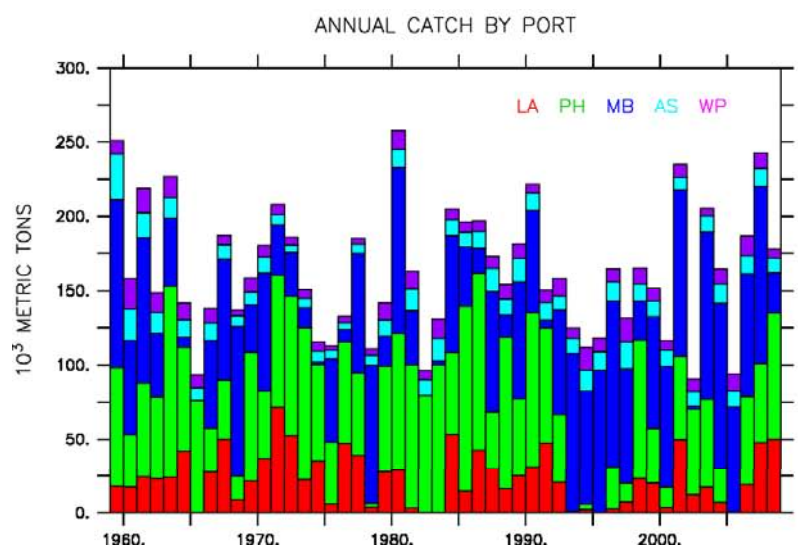
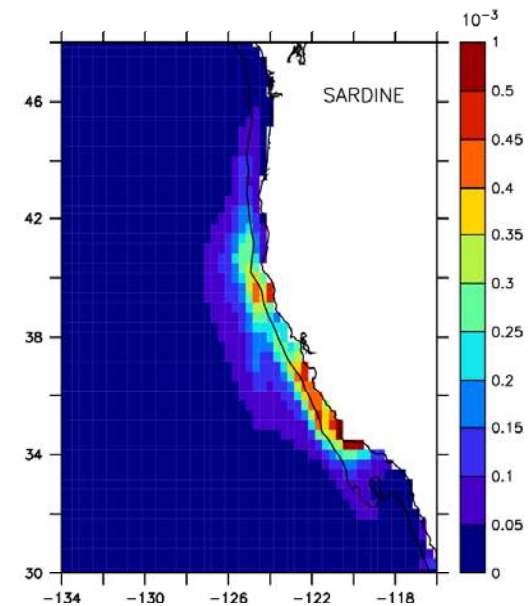
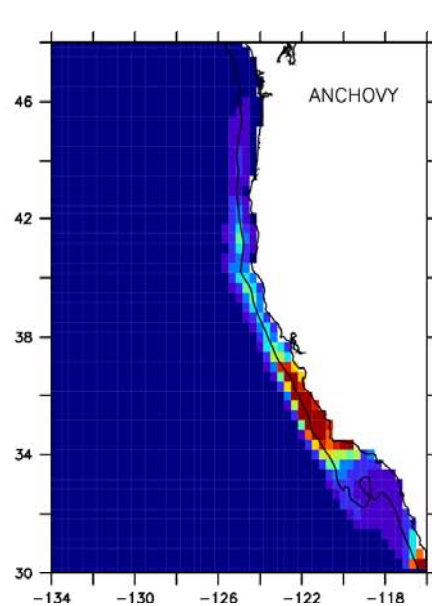
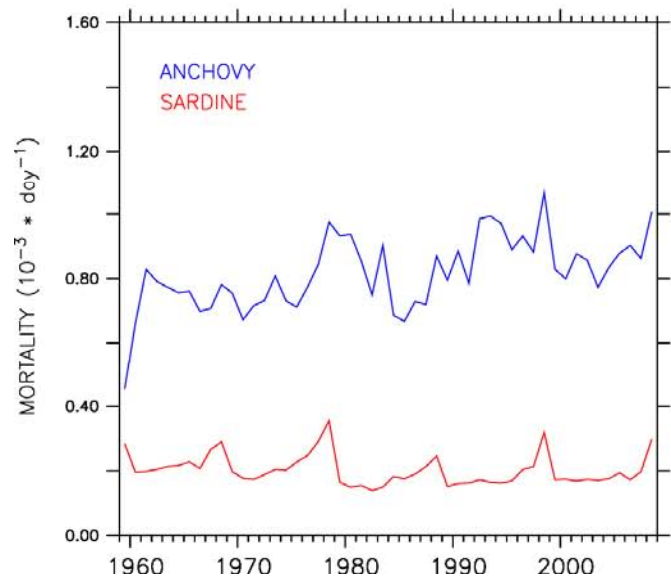


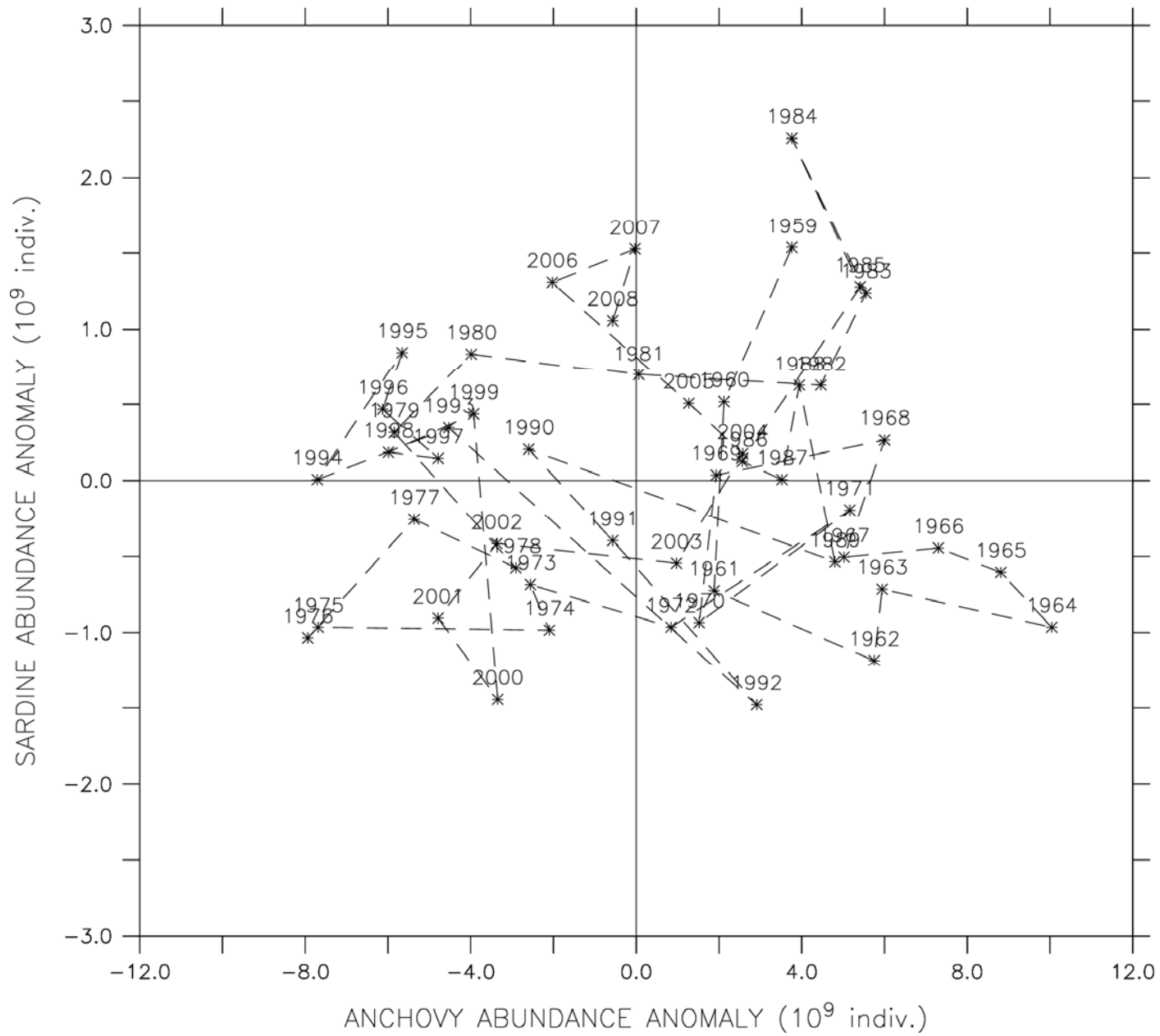
ANCHOVY



SARDINE



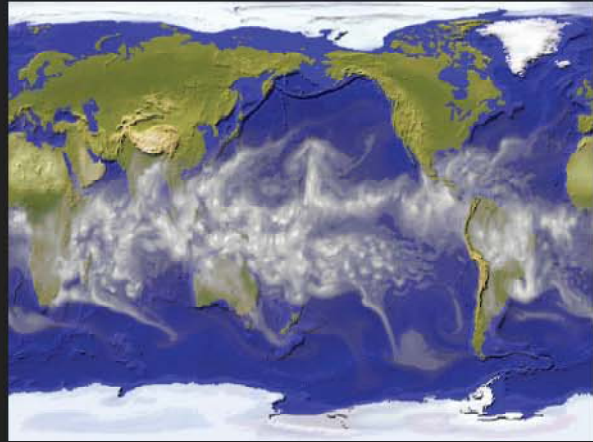




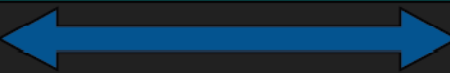
Next Steps

- It can be done – proof of principle
 - Bookkeeping solved
 - Linkages operating (interpolation)
 - Parallel computing working
- Parallel effort for Oyashio-Kuroshio system underway (Dr. Ito)
- Implementation within Earth System Model

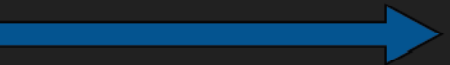
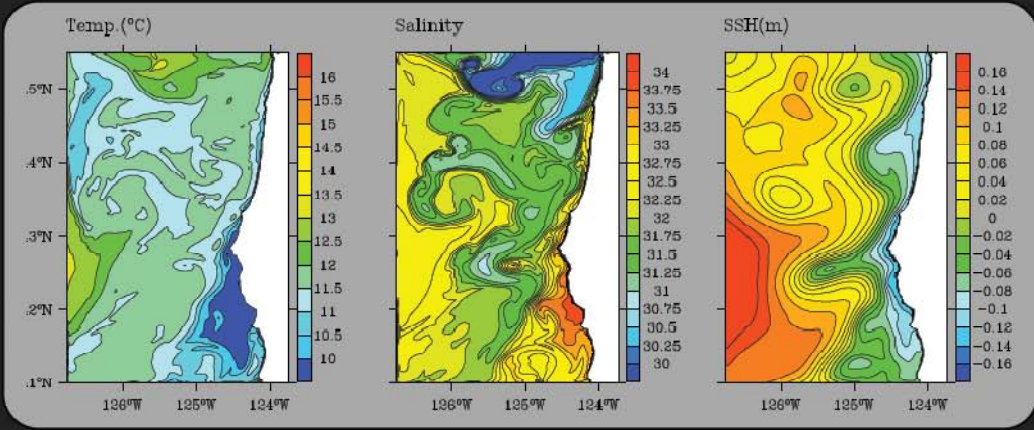
NCAR-CCSM Global Climate Model



Dynamical two-way downscaling

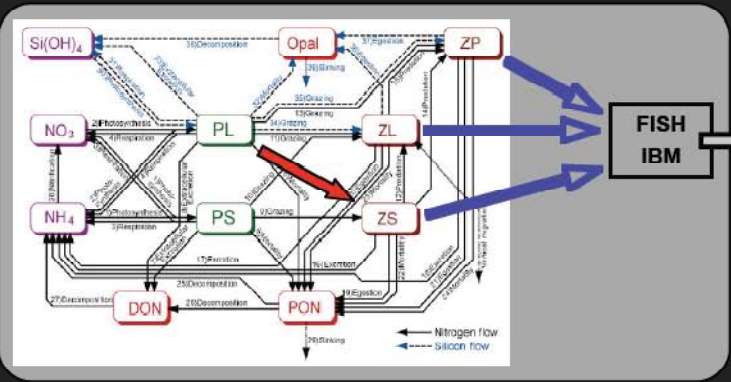


ROMS regional ocean model



Tightly coupled to lower and upper trophic level models

NEMURO NPZD and Individual Based Model



Growth
Reproduction
Mortality
Movement

Fishing fleet



So is it Useful?

- Include important differences in the species
- Extensive historical data for model evaluation
- Evaluate hypotheses of cyclic dynamics
 - Bottom-up: transport and circulation
 - retention, eddies, upwelling, source water
 - Bottom-up: temperature optima and NPZ (food)
 - Top-down: loopholes, predator shift, fisheries

End-to-End Modeling of
Marine Ecosystems: can the
people and data keep up with
the computers?

Kenneth Rose
Louisiana State University

Introduction

- Accelerating interest in end-to-end models
- End-to-end means climate to physics to fish to fisheries to people
- Conceptually and politically attractive

Introduction

- To date, physics-NPZ and fish models were developed separately
- Meet at zooplankton (fish food)
 - Closure term for NPZ
 - Assumed available for fish
- Advances in each seemed out-of-phase
- Today: thoughts about end-to-end modeling

Why now?

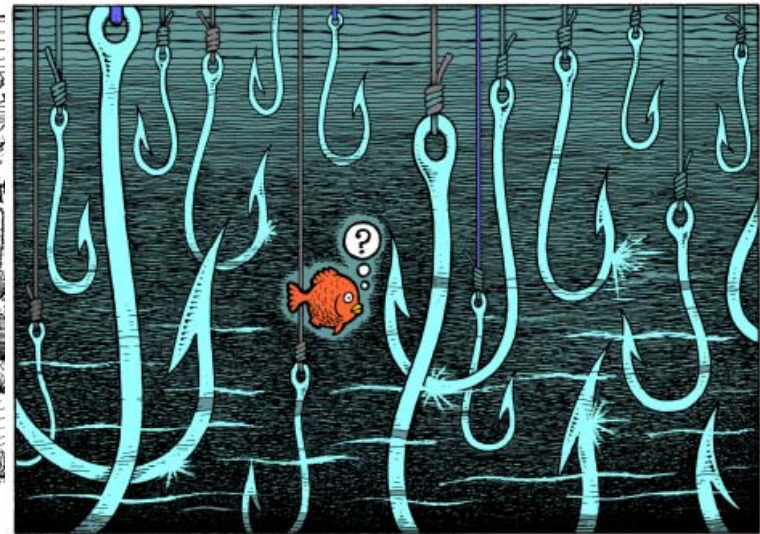
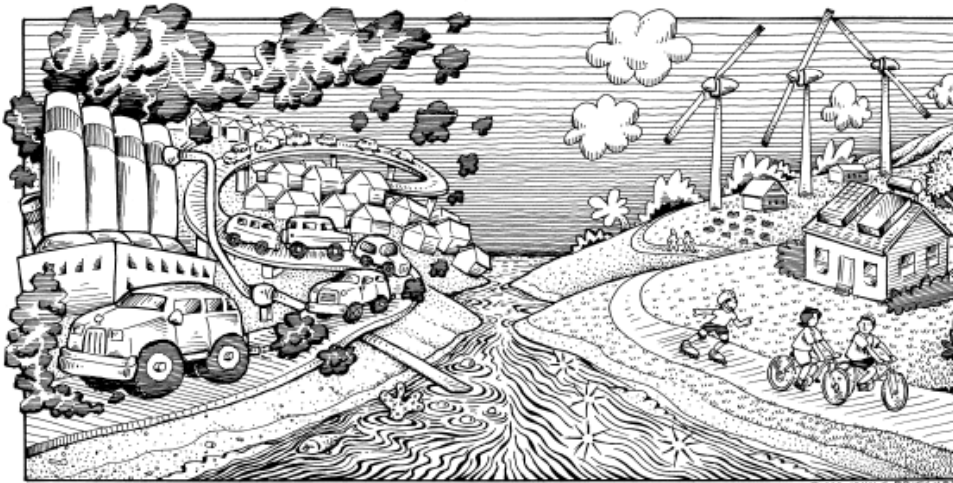
- Advances in data collection
 - Spatially-detailed data
 - Behavioral measurements
- Continued increases in computing power
- Advances in modeling
 - Physics: meso-scale features in decadal runs
 - Fish: individual-based, fine-scale observations

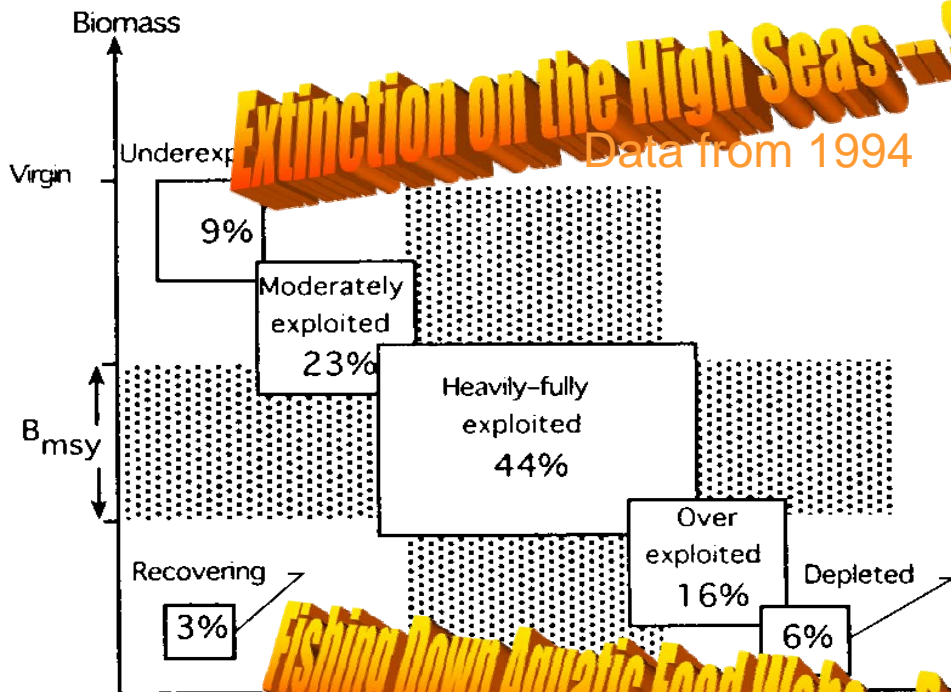
Technical: Computing

- Computing power is constantly surprising us (especially older scientists)
- Super-computers, OPENMP

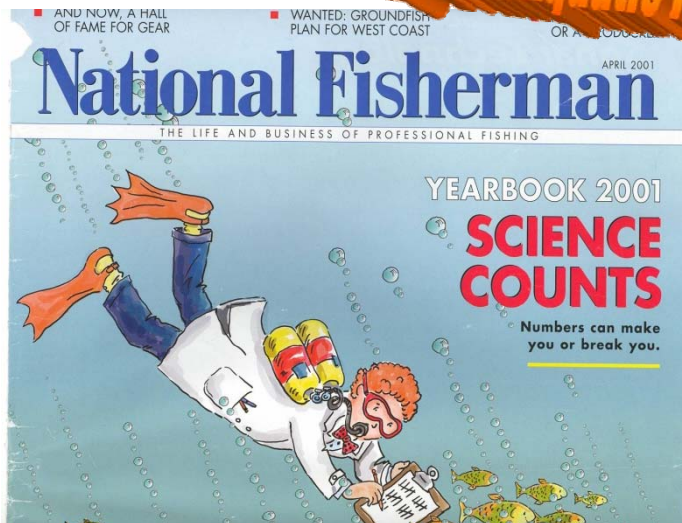


What's Changed?



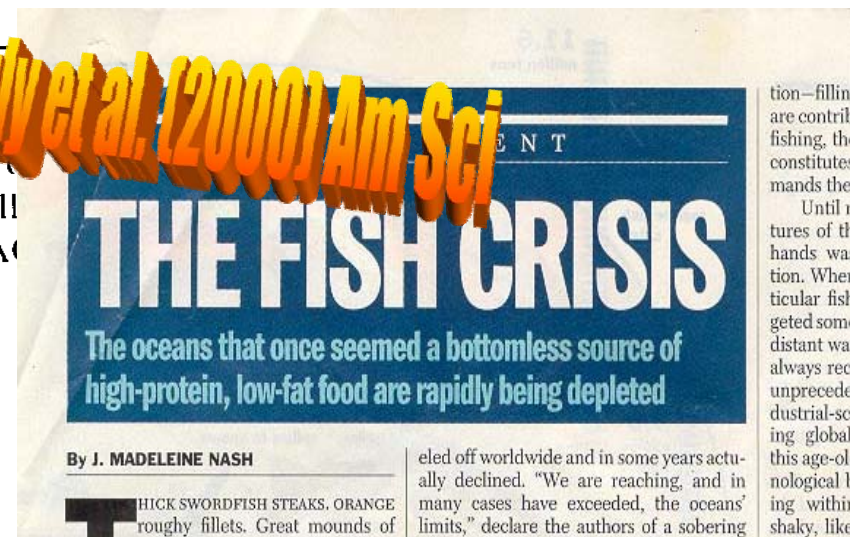


1996!



Fishing Down Aquatic Food Webs - Pauly et al. (2000) Am Sci

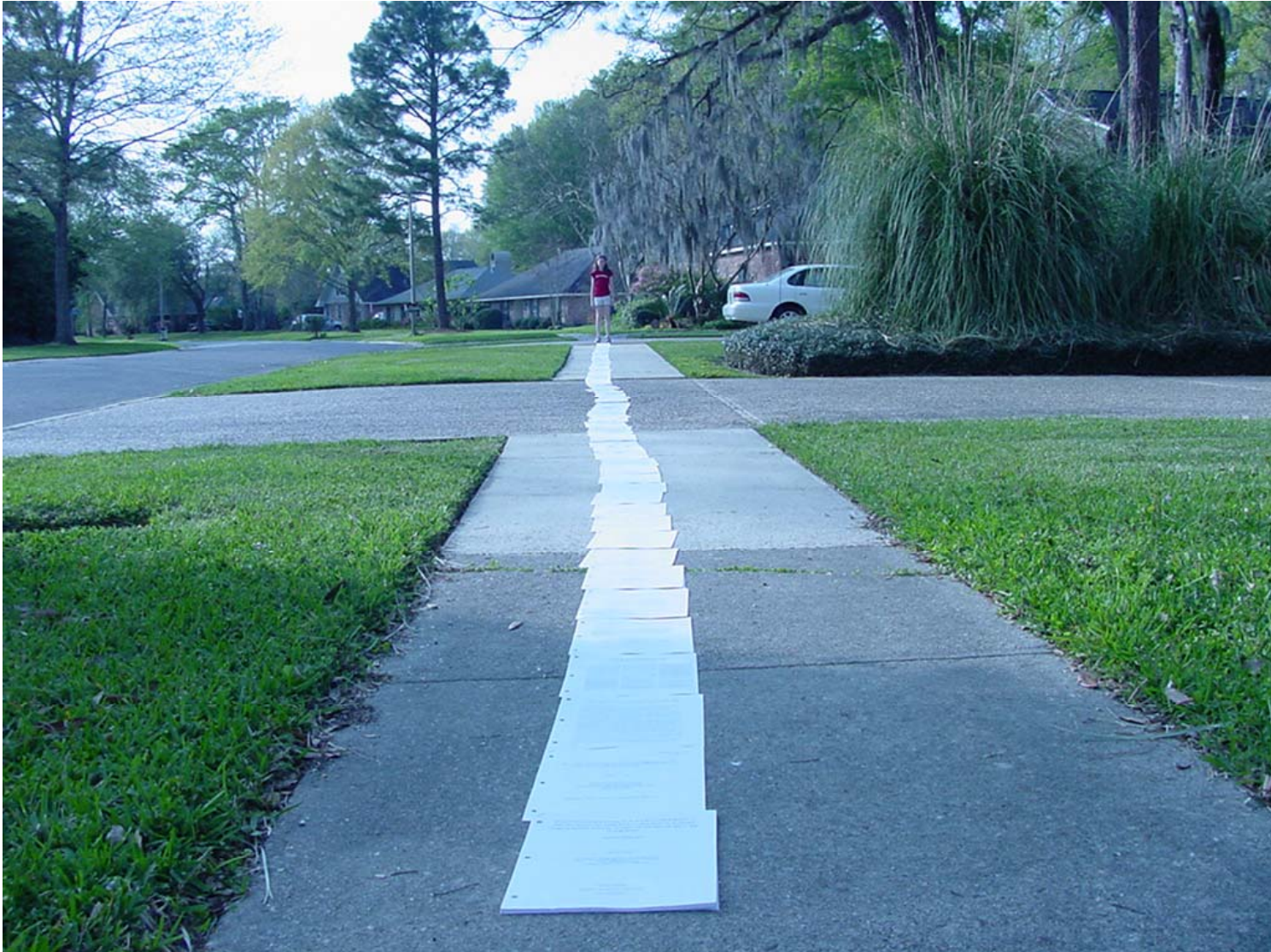
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eled off worldwide and in some years actually declined. "We are reaching, and in many cases have exceeded, the oceans' limits," declare the authors of a sobering

Preparation documents sent to review panel members for the Gulf of Mexico Red Snapper stock assessment



One Solution

- Coupled models that can address bottom-up, top-down, and side-ways issues
- Climate change effects on fish
- Perceived fisheries management crisis due to simple single-species approach
- Ecosystem-based management (whatever that means)

Challenge

- How to combine models with different temporal and spatial scales
- No general theory
 - Modeling as art
- Including human dimensions
- Working across disciplines



Approaches to end-to-end ecosystem models

Elizabeth A. Fulton*

CSIRO Marine Research, GPO Box 1538, Hobart, Tasmania 7001, Australia

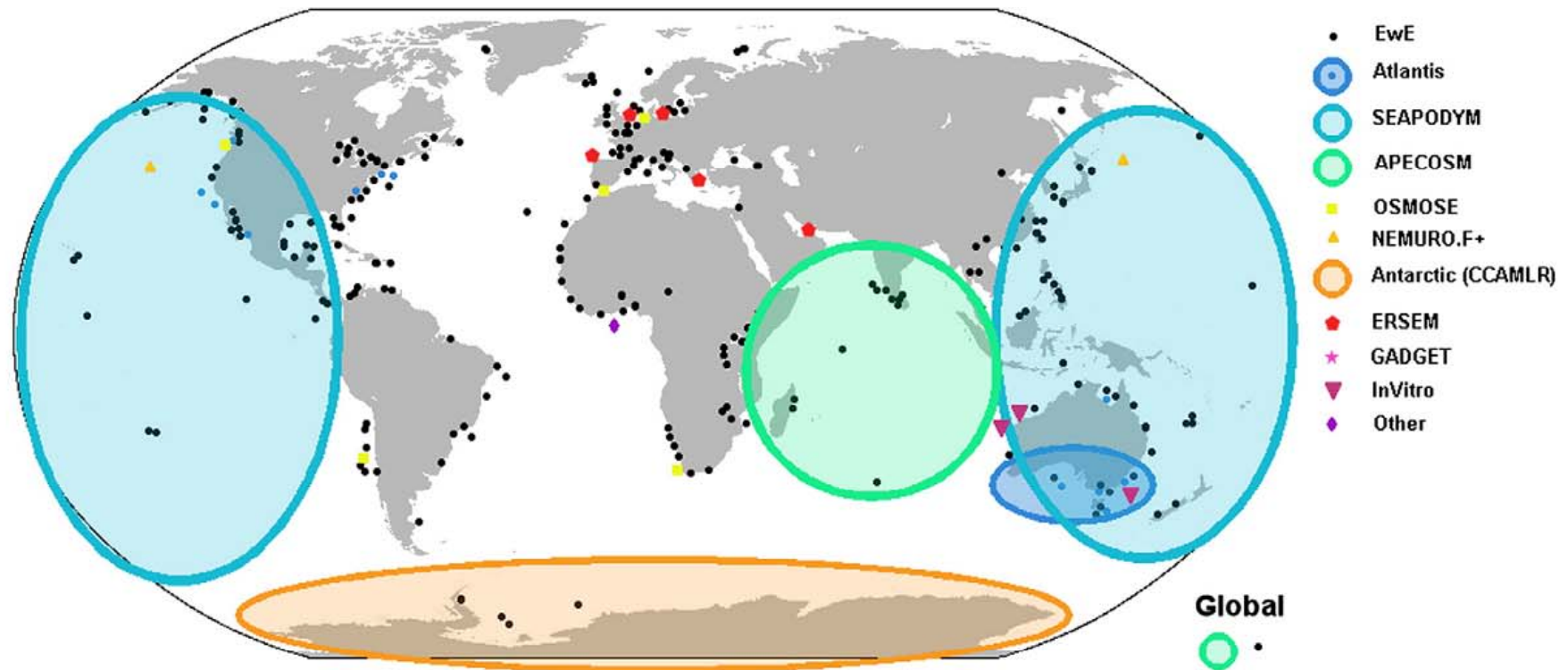


Fig. 3. Map of end-to-end models implemented to date (many more have been proposed or are in early development).

End-To-End Models for the Analysis of Marine Ecosystems: Challenges, Issues, and Next Steps

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**“Bridging the gap between
lower and higher trophic
levels”**

February 2009
Plymouth, England
AMEMR and MEECE



Issues

(1) Zooplankton

Shift from biochemical cycling to fish food

(2) New Organisms

Macroinvertebrates

Demersal fish species

People

Issues

(3) Scaling

Determining the appropriate temporal, spatial, and biological scales for a model is always challenging

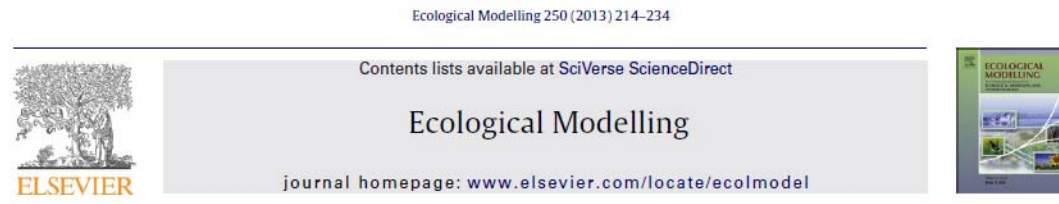
Now,

- Hydrodynamics on minute scales
- Organisms that live for days to decades
- 10^{-12} to 10^6 grams
- Fast processes (e.g., larval feeding) for decades
- Fine-scale but large domain and near coasts
- Interspecific interactions – community ecology has failed us

Issues

(4) Acclimation and adaptation

(5) Behavioral movement



Evaluating the performance of individual-based animal movement models in novel environments

Katherine Shepard Watkins*, Kenneth A. Rose

Department of Oceanography and Coastal Sciences, Energy, Coast, and Environment Building, Louisiana State University, Baton Rouge, LA 70803, United States

(6) Software

C and FORTAN

Hinders advances

Issues

(7) Solution and numerics

Two-way coupling

Super-individuals

Full life cycle

Eulerian and Lagrangian

Density-dependence

Computing

Issues

(8) Model confidence

Physics people need to relax a bit

(9) Interdisciplinary Efforts

Move from multi to interdisciplinary

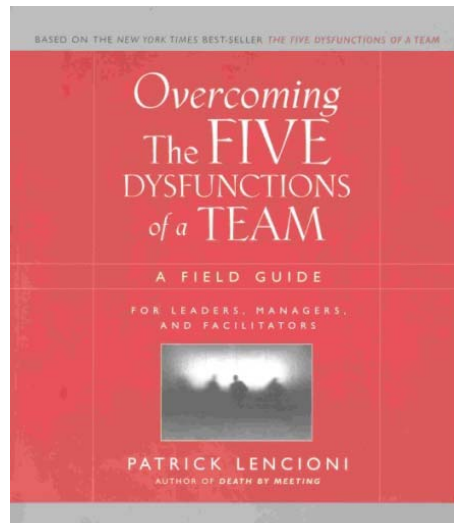
Adjustment of plans based on others

Issue 9

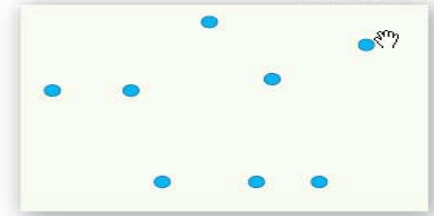
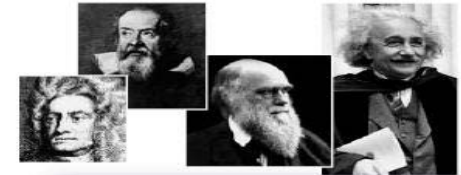
Barabasi 2005



"You should check your e-mails more often. I fired you over three weeks ago."



Galileo Newton
Darwin Einstein



Crick and Watson



International Human
Genome Sequencing
Consortium



Conclusions

- Ingredients are now available
- It can (should) be done!!
 - Decisions are being made, without the best information
- Challenges:
 - Technical (computing, algorithms, data)
 - Institutional
 - People



Rose (2012) End-to-end models for marine ecosystems:
Are we on the precipice of a significant advance or
just putting lipstick on a pig? *Scientia Marina* 76:195-201.



What we want to avoid

Over-promise
Repackage poorly performing submodels
Frakenmodel
Call everything “end-to-end”

Community-based effort
Collaborative
Caution and thoughtful
Face our weaknesses

Unsolicited Advice

- Do not love your model - it will not love you back
- Do not apologize for your model
- Take ownership and responsibility of the model, while respecting its history
- You should know what the mathematics is and the solution method you are using
- Precision versus accuracy and relative predictions versus forecasting

Unsolicited Advice

- Very carefully use computer costs as basis for assumptions
- Learn to program in a sequential language
- Test codes with known problems in modules
- Try to break the model and then treat model simulations as an experiment

Unsolicited Advice

- Lead the audience from model output to final figures you show
- Know your audience
- Know the details of model even if you inherited it from someone else
- Simple assumptions are the most important
- Hidden assumptions will get you

Unsolicited Advice

- Understand why results occurred
- Trace history of model before the most recent paper
- Respect data but not wait for it
- Embrace variability, feedbacks, and interactions
- Learn how to bound the answers

End-to-End Modeling: Simulating Movement of Fish over Spatial and Temporal Scales:

*if fish were dumber and people were smarter
Is it the journey or the destination?*

Kenneth Rose
Louisiana State University
Baton Rouge, LA USA

Movement

- A major challenge is modeling movement
 - Eggs and larvae maybe reasonably simulated with particle-tracking
 - Juveniles and adults require behavioral approaches
- Wide range of temporal and spatial scales
 - Often scales determined by other submodels
 - Compatibility issues

Movement

- Many approaches have been proposed
 - $X(t+1) = X(t) + V_x(t)$
 - $Y(t+1) = Y(t) + V_y(t)$
 - $Z(t+1) = Z(t) + V_z(t)$
 - Determine the cell
- Quite confusing because of non-standard descriptions and terminology for V_x , V_y , and V_z
 - Random walk
 - Run and tumble
 - Event-based
 - Restricted-area
 - Kinesis
 - ANN



Movement Issues

- Fixed parameters preventing adaptive and phenotypic variation in behavior
- Edge effects on finite grids
- Stranding and oscillatory movements
- Weakly convergent parameter values
- Non-unique pattern matching

Issues

- Renegade individuals
- Bifurcated movement patterns
- Short-cut solutions that use geography
- Compromise behaviors from multiple cues
- ***Calibration and validation***

Major Issue

- If we are to use these methods to simulate management actions and climate change, then the methods must capture the response to cue(s)
- Little investigation of performance of any of these approaches under novel conditions
- We will explore this issue in more detail

Calibration and Validation

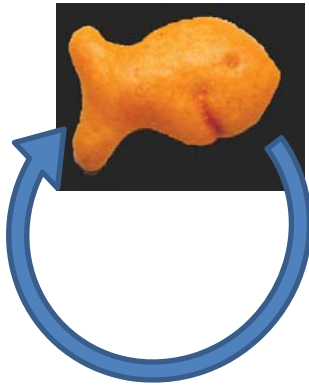
- Challenge: Calibration data are rarely available at the necessary scale
- Genetic algorithms calibrate without data by evolving a population with parameters that produce fit movement
- GAs assume fish inherit movement instincts that maximized fitness in previous generations
- Examples: ANNs (Huse and Giske 1998; Huse and Ellingsen 2008; Mueller et al. 2010), neighborhood search (Giske et al. 2003), rule-based (Huse 2001)

Calibration and Validation

- Calibrate 4 movement models (neighborhood search, kinesis, event-based, and run-tumble) with a GA in four 2-D environments
- Evaluate the performance of each calibrated sub-model in novel conditions

Model Structure

**Simplified
Hypothetical
Species**



Scale

Grid: 540 x 540 cells

Cells: 5 m²

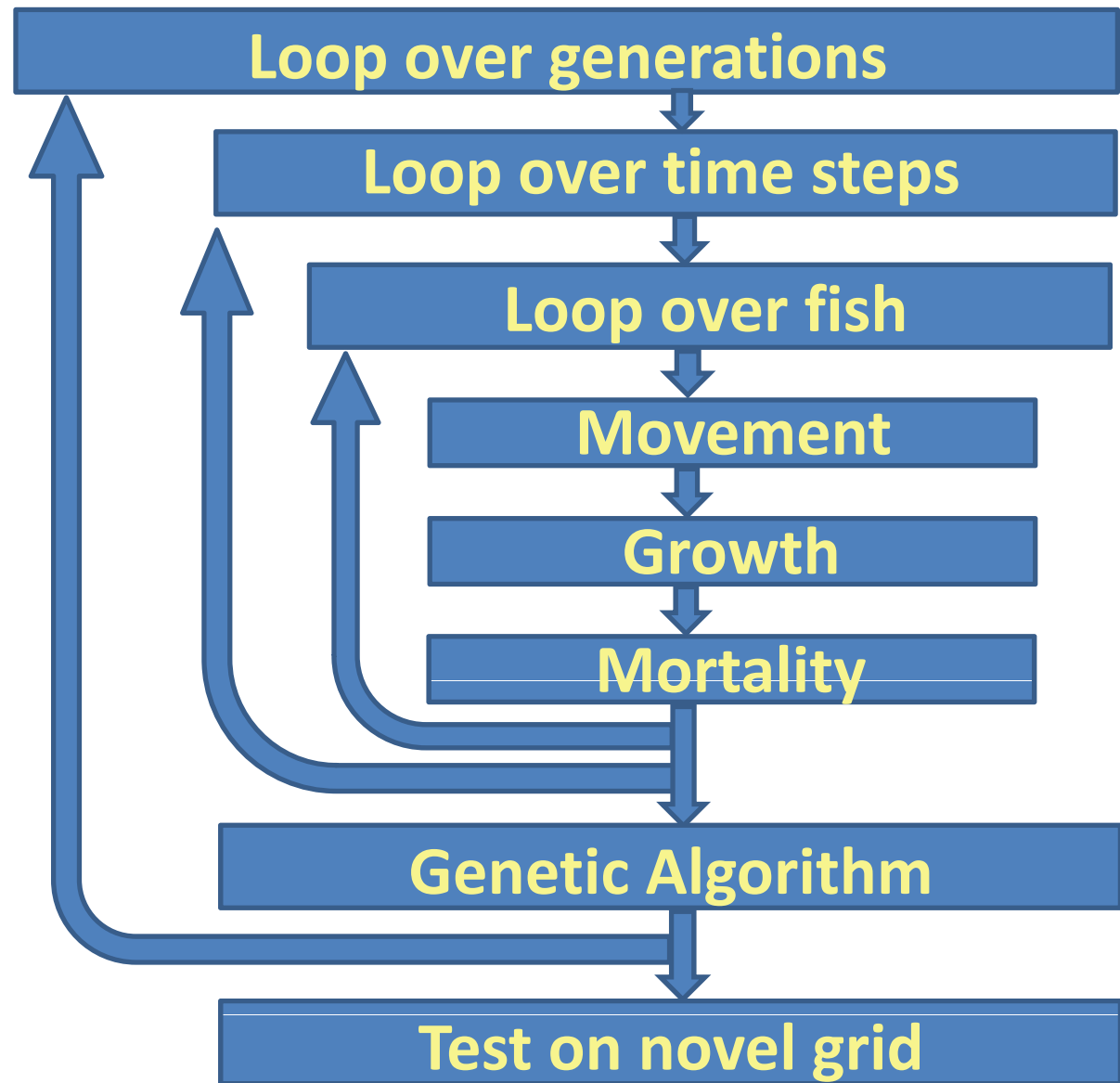
Time step: 5 minute

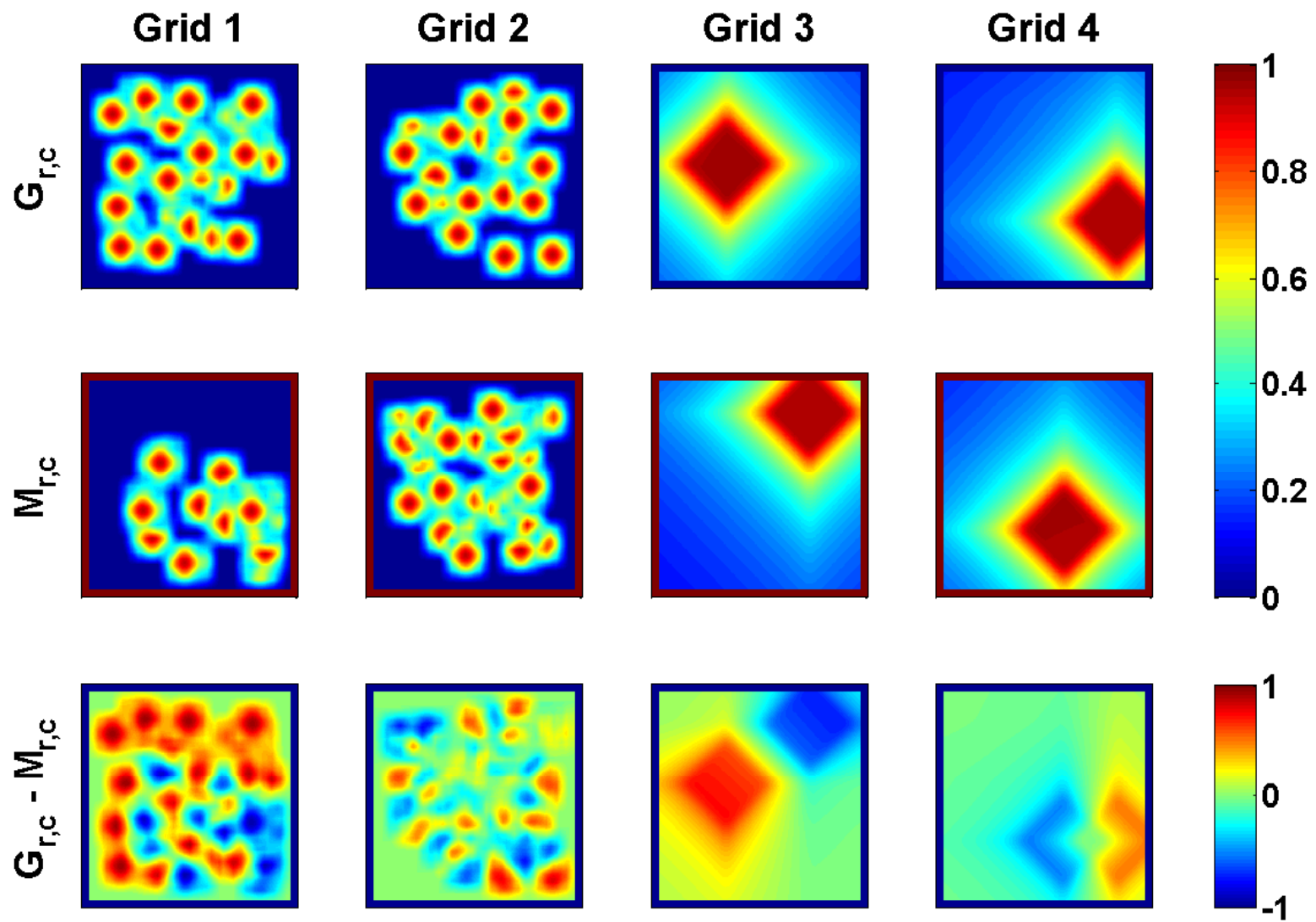
Generation: 30 days

Initial size = 73.3 mm

Initial worth = 100 fish

3000 super-individuals





Patchy
No trade-offs
Patchy
Trade-offs
Smooth
No Trade-offs
Smooth
Trade-

Model Processes

Growth (mm 5-min⁻¹)

$$G = G_{\max} * G_{r,c}$$

$$L(t+1) = L(t) + G$$

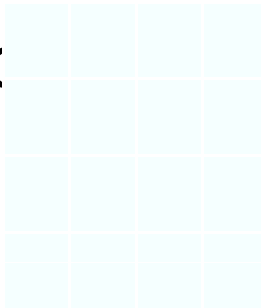
$$W(t+1) = a * L(t+1)^b$$

Movement

$$X(t+1) = X(t) + V_x(t)$$

$$Y(t+1) = Y(t) + V_y(t)$$

cell location (r,c)



Mortality (5-min)⁻¹

$$M = M_{\max} * M_{r,c} * M_L$$

$$S(t+1) = S(t) * e^{-M}$$

$$M_L = 1 - \frac{L_i^{-73.3}}{L_{\max}^{-73.3}}$$

Reproduction

$$E = 55 * S(30) * (421.84 * W(30) + 304.79)$$

GA Calibration

- 3000 strategy vectors of parameter values
 - Start with random values for everyone
- Every 30-day generation, select 3000 individuals:
 - $P(\text{selection}) = E_i / \Sigma E$
 - Mutate each vector: 6% of parameters, ± 0.25
- Use these 1000 vectors for the next generation
- Continue until egg production levels off
- Parameter values should have converged

Restricted Area Search

- Rank cells in a D_{hood} cell radius by habitat quality ($Q_{c,r}$)

$$Q_{c,r} = (1 - \delta) * (G_{c,r} + n) - \delta * (M_{c,r} * M_L + n)$$

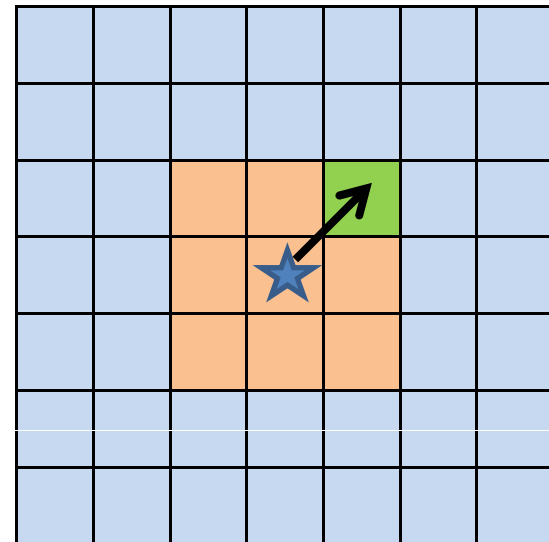
- $n = \left(1 - \frac{1.42}{\sqrt{(c-xcell)^2 + (r-ycell)^2}} \right)$

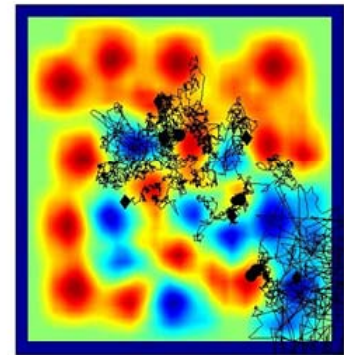
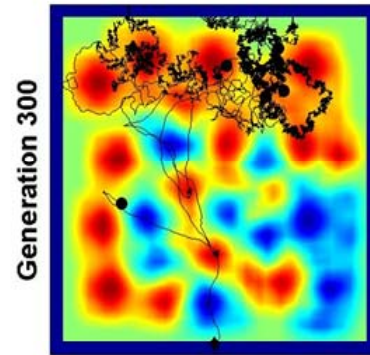
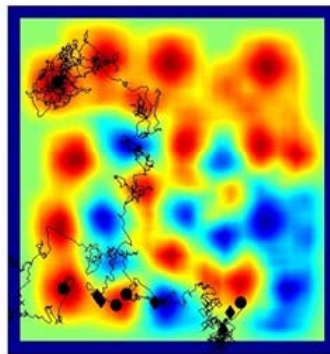
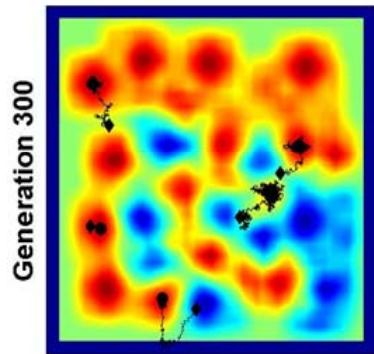
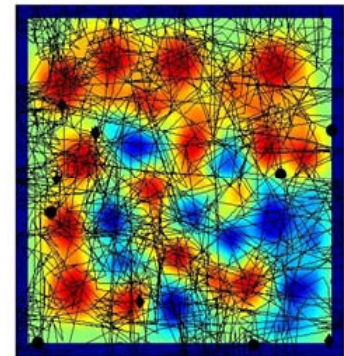
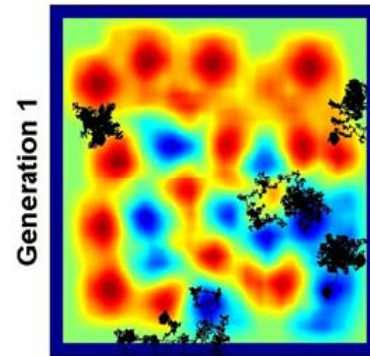
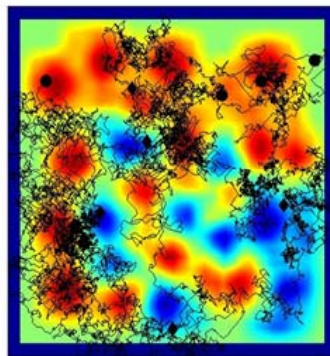
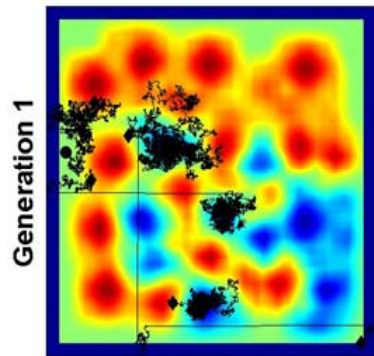
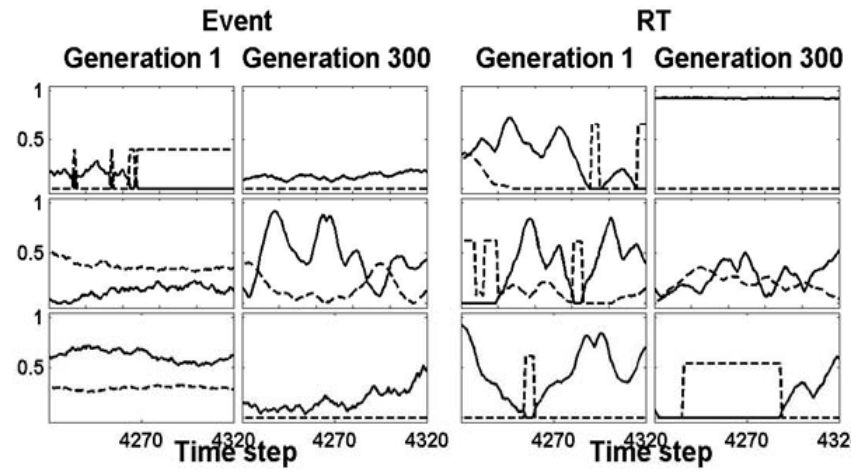
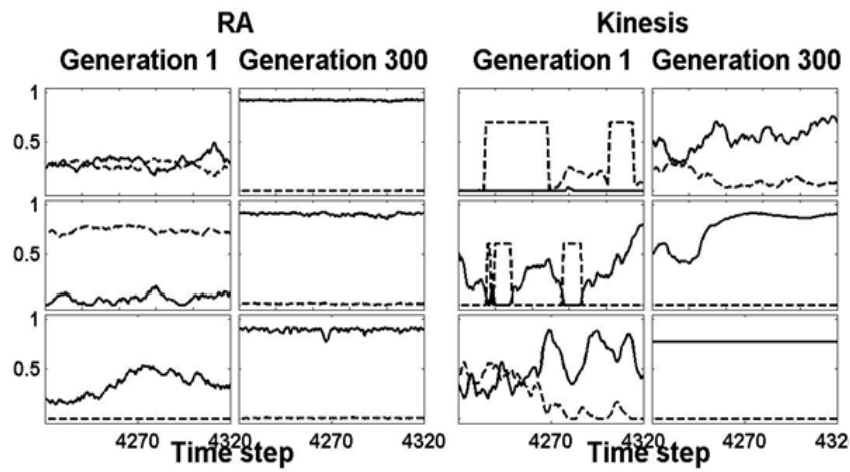
- Compute Θ = toward the cell with the highest $Q_{c,r}$

$$V_x(t) = (SS + RV_1 \cdot R_{dist}) \cdot \cos(\theta + RV_2 \cdot R_\theta)$$

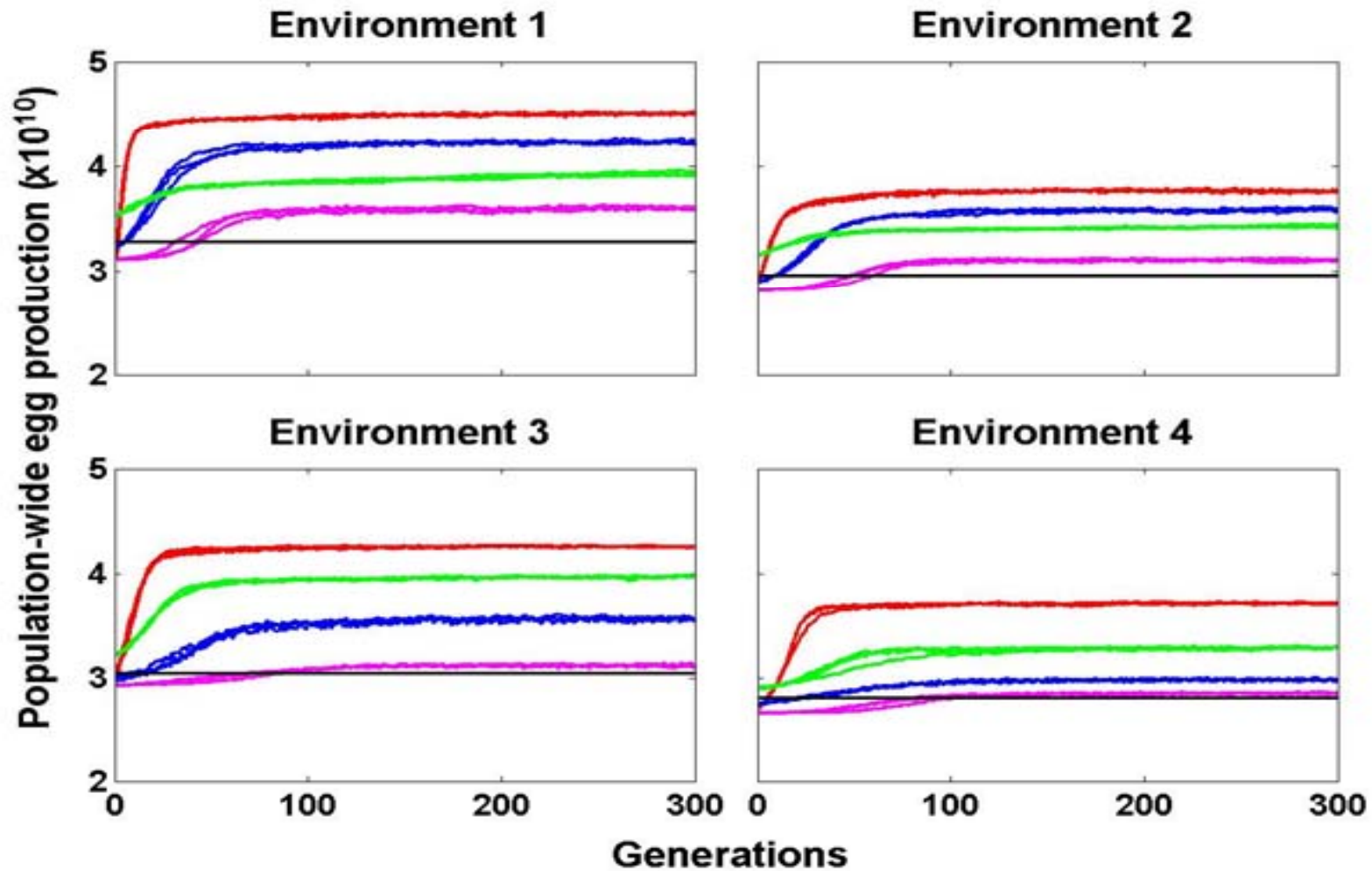
$$V_y(t) = (SS + RV_1 \cdot R_{dist}) \cdot \sin(\theta + RV_2 \cdot R_\theta)$$

- GA evolves: δ , R_θ , R_{dist} , D_{hood}



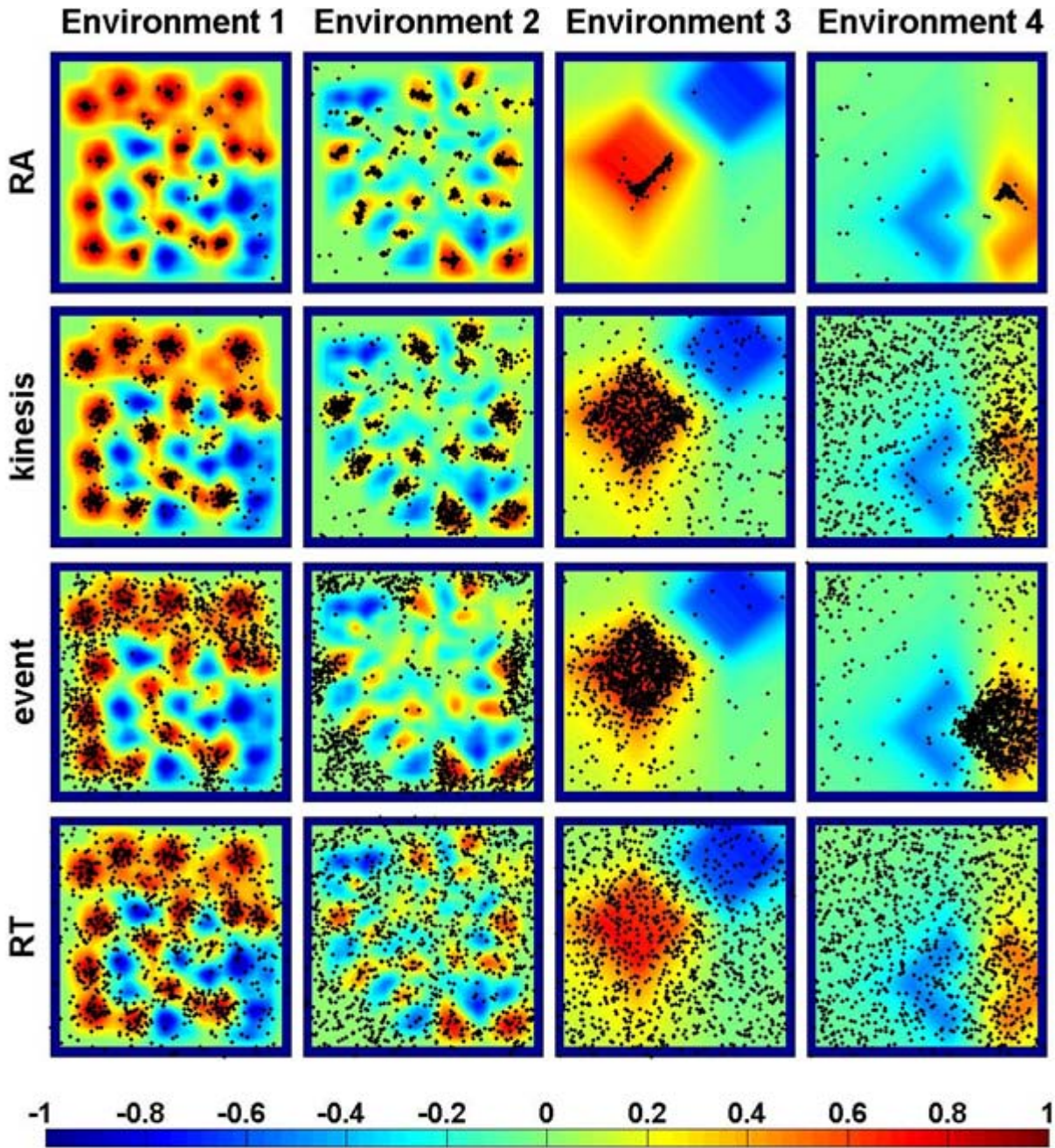


Calibration – Fitness Convergence

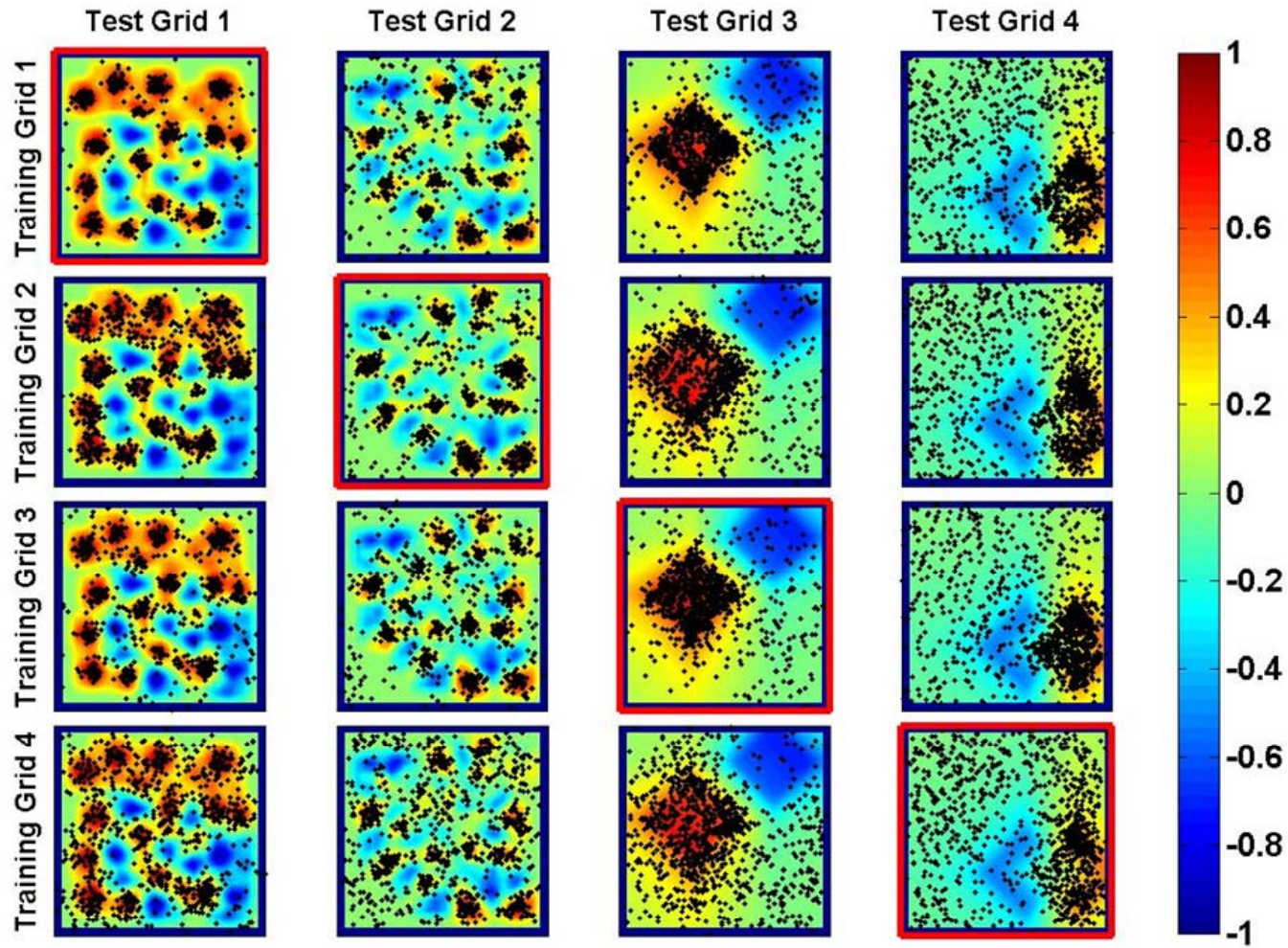


Restricted area, Kinesis, Event-based, Run-tumble

Last day
of 300th
generation



Kinesis - Testing



Conclusions

- Behavioral movement is a major uncertainty in spatially-explicit models
- Presently, a variety of approaches whose relationships are unclear and developed on different scales
- Our analysis attempted to address this:
 - Calibration - GA
 - Robustness - testing under novel conditions